



Introduction to OpenMP

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1. Increase performance / throughput of CPU core

- a) Reduce cycle time, i.e. increase clock speed (Moore)
- b) Increase throughput, i.e. superscalar + SIMD

2. Improve data access time

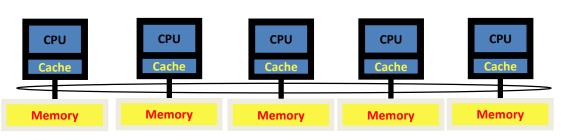
- a) Increase cache size
- b) Improve main memory access (bandwidth & latency)

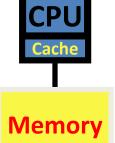
3. Use parallel computing (shared memory)

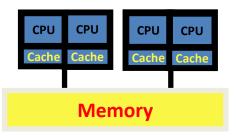
- a) Requires shared-memory parallel programming
- b) Shared/separate caches
- C) Possible memory access bottlenecks

4. Use parallel computing (distributed memory) *"Cluster" of computers tightly connected*

- a) Almost unlimited scaling of memory and performance
- b) Distributed-memory parallel programming





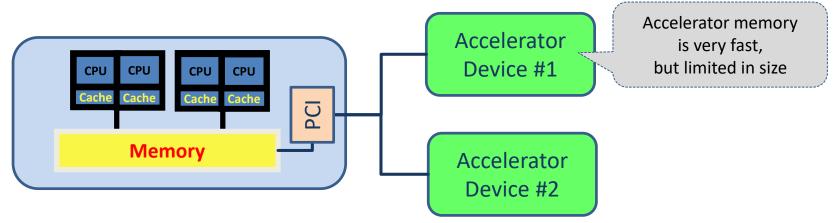






5. Use an accelerator with your compute node

- a) Requires offload of program regions (semantics may be limited)
- b) Host and accelerator memory are connected, but separate



(Improvements are under way)

 C) Programming complexity is higher than for shared memory systems ("heterogeneous parallel computing")

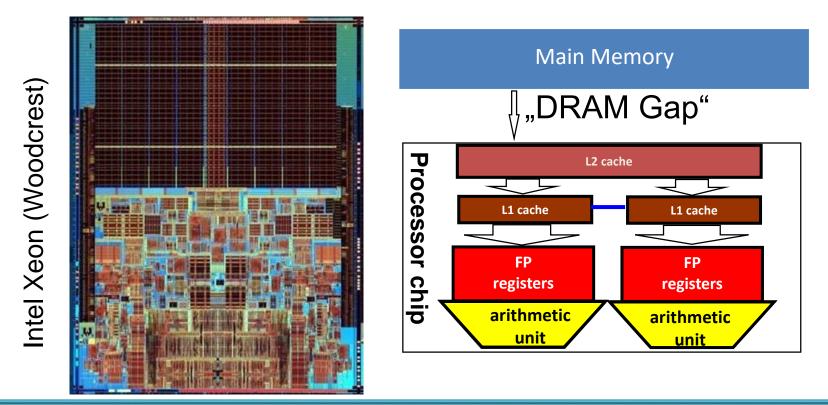




It is not a faster CPU – it is a parallel computer on a chip.

Put multiple processors ("cores") on a chip which share resources (example shows a dual core that shares L2 cache and memory bandwidth)

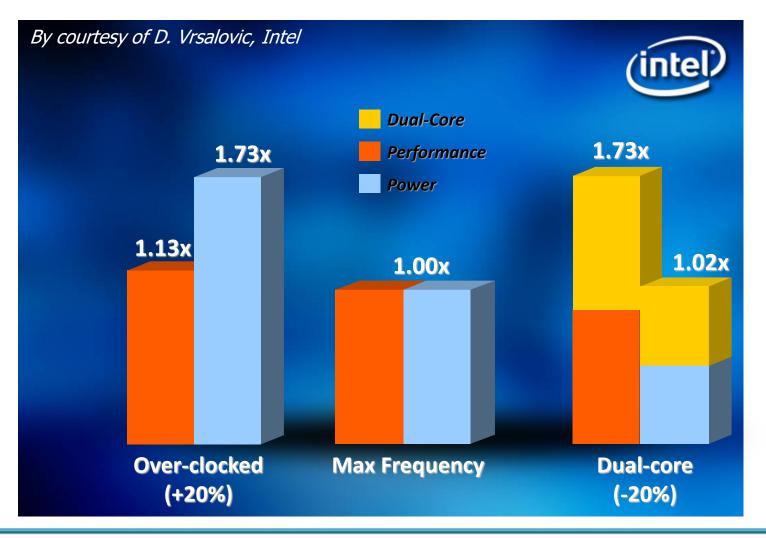
Efficient use of all cores for a single application \rightarrow programmer





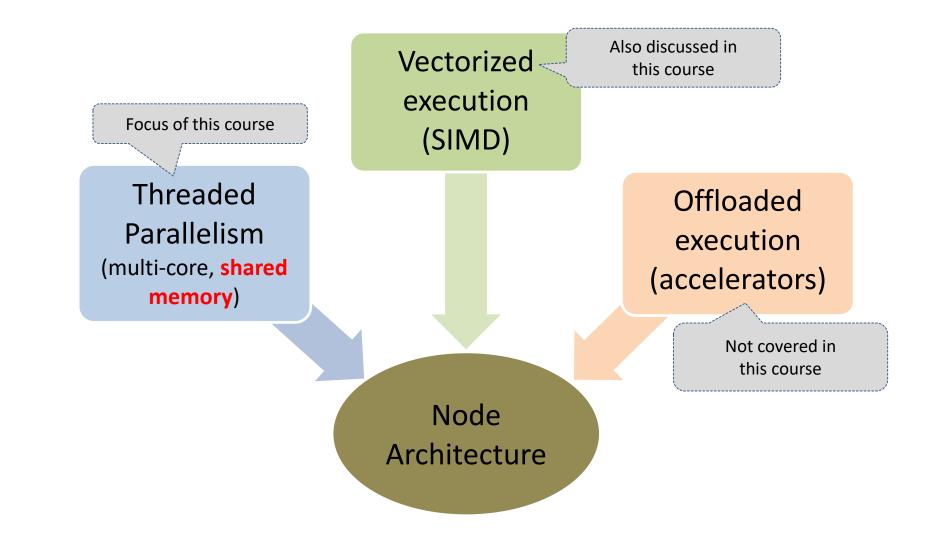


Option 1 a) is not feasible any more, option 2 only in small increments













Syntactic portability

- Directives / pragmas
- Conditional compilation permits to masks API calls

Semantic portability

- Standardized across platforms
 → safe-to-use interface
- Unsupported/unavailable hardware features → irrelevant directives will be ignored (you might need a special compiler for your devices ...)

Performance portability

- Unfortunately performance is not necessarily portable
- Has traditionally been a problem (partly due to differences in hardware/architectural properties)





Are semantics for sequential execution retained?

- yes, due to directive concept
- programmer may choose not to

Do memory accesses occur in the same order?

 no, due to relaxed memory consistency (performance feature!)

Are the same numeric results obtained for parallel execution?

- no associativity for model number operations
- parallel execution might reorder operations (programmer may need to enforce ordering for reproducibility and/or numeric stability)

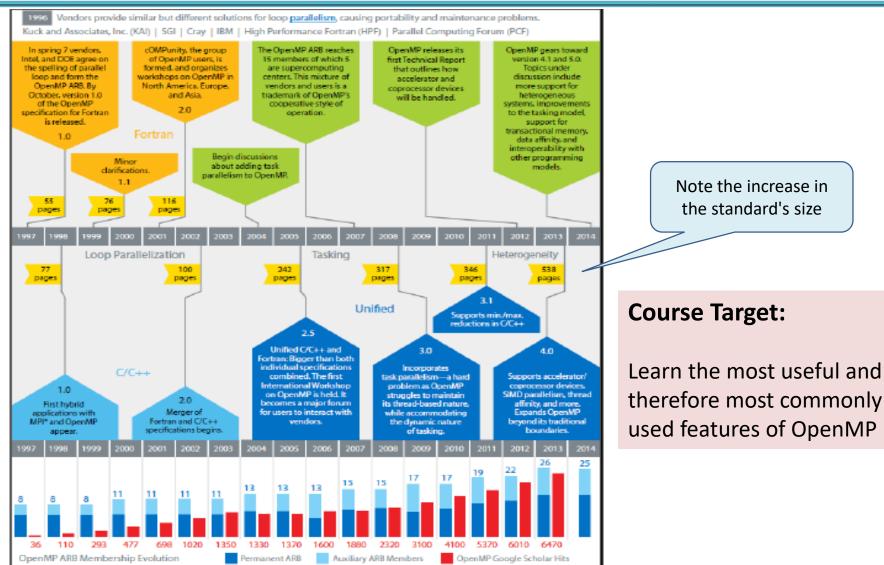




- - <u>http://www.openmp.org</u> (including standard documents)
 - <u>http://www.compunity.org</u>





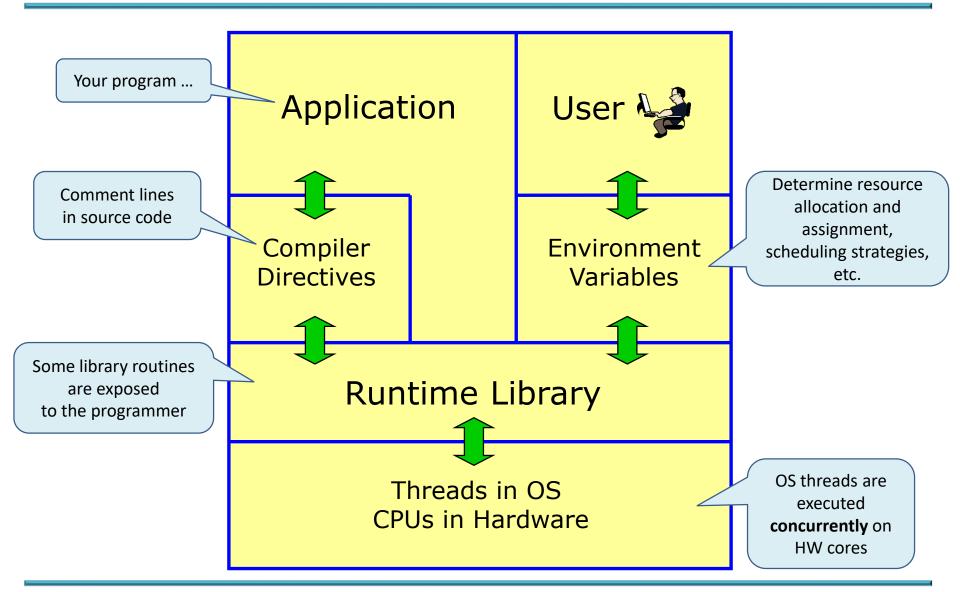


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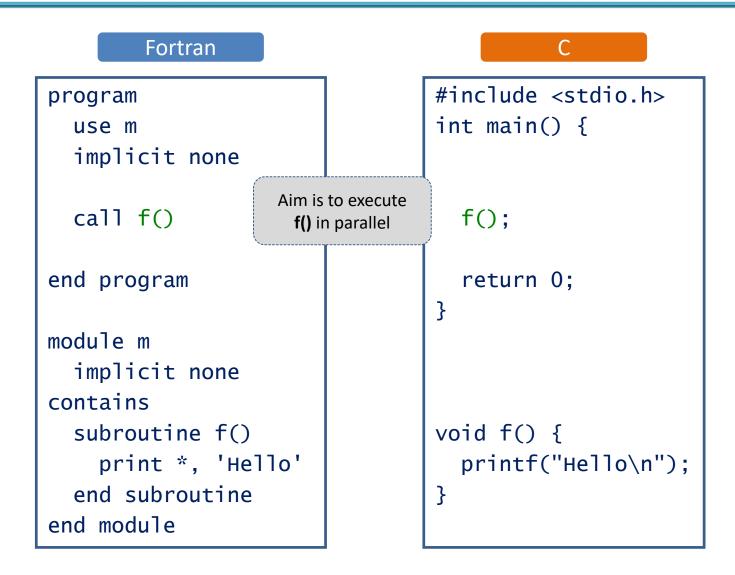








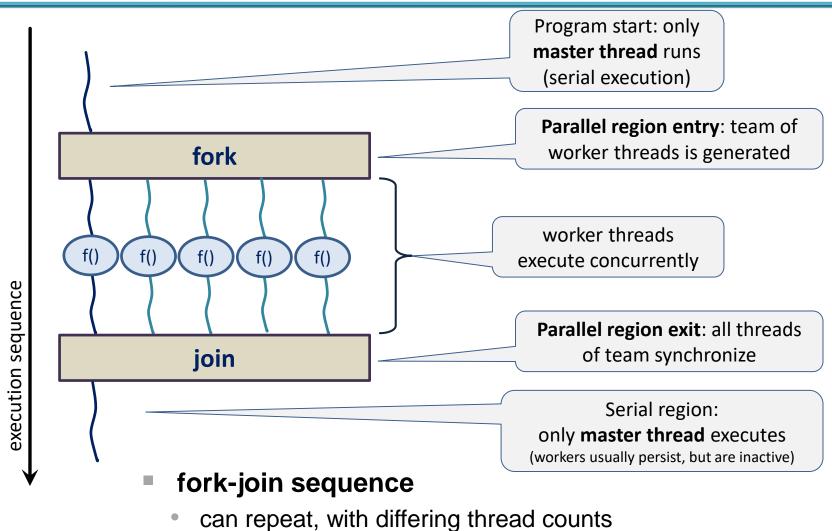




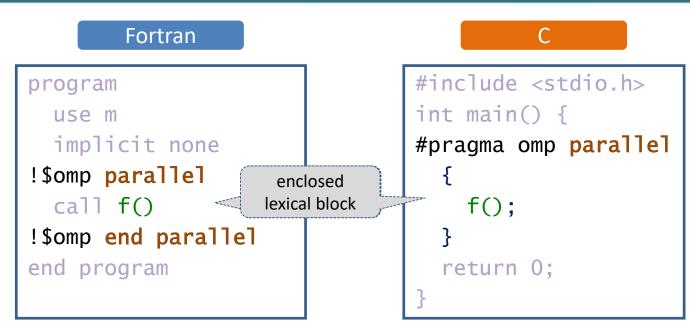


Parallel execution model

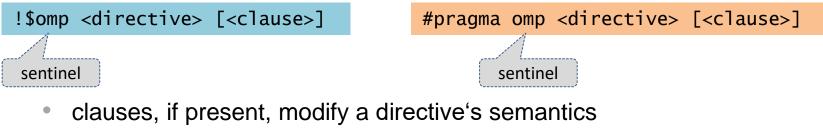








General form of directives:



- multiple clauses per directive are possible
- continuation lines are supported for long directives:

Fortran

&



Fortran

 statements between a beginning and ending directive pair

C / C++

 delineated by braces following a directive

single point of entry

GOTO into block is prohibited

setjmp() into block is prohibited

single point of exit

 GOTO, RETURN, EXIT outside block are prohibited longjmp() and throw() outside block are prohibited

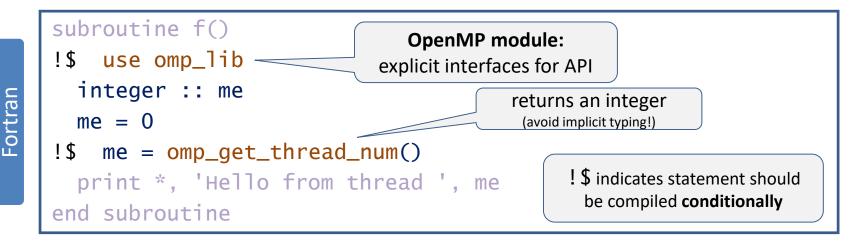
permitted: program termination

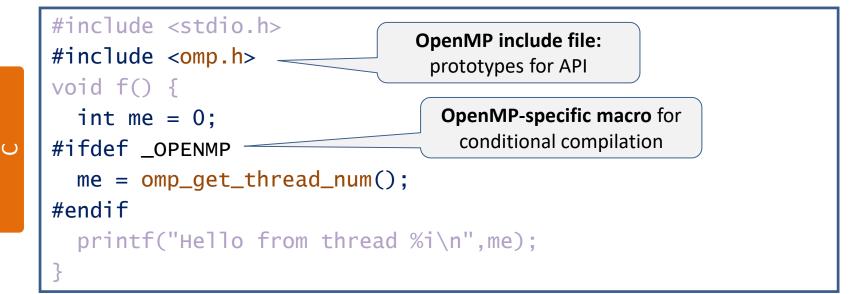
• STOP, ERROR STOP

exit()









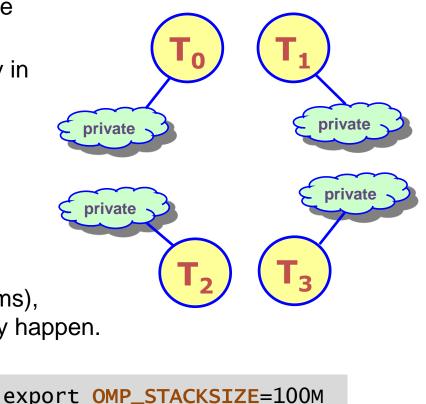




- As many independent function calls as there are threads
- Thread-individual memory management within function call
 - local variables ("me") are created in the thread-specific stack
 - malloc() or ALLOCATE create memory in the heap separately for each thread
- Private variables
 - associated with a particular thread are inaccessible by any other thread
 - pro: safe to use
 - con: communication is not possible (it is needed by many parallel algorithms), unnecessary replication of objects may happen.

Thread-individual stack limit

 control via environment variable (example: 100 MByte)







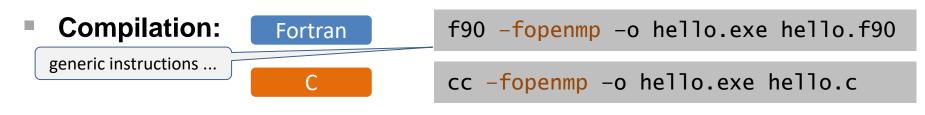
Classes of routines:

• Execution environment (36), Locking (12), Timing (2), Device Memory (7)

	Name	Result type	Purpose
	omp_set_num_threads (int num_threads)	none	number of threads to be created for subsequent parallel region
subset	<pre>omp_get_num_threads()</pre>	int	number of threads in currently executing region
used	<pre>omp_get_max_threads()</pre>	int	maximum number of threads that can be created for a subsequent parallel region
commonly	<pre>omp_get_thread_num()</pre>	int	thread number of calling thread (zero based) in currently executing region
	<pre>omp_get_num_procs()</pre>	int	number of processors available
most	<pre>omp_get_wtime()</pre>	double	return wall clock time in seconds since some (fixed) time in the past
	<pre>omp_get_wtick()</pre>	double	resolution of timer in seconds





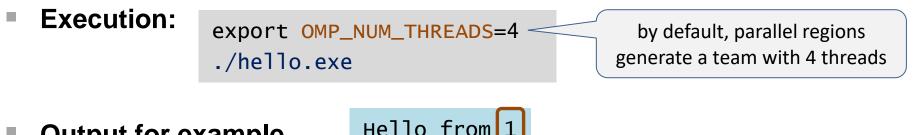


Switch for OpenMP

- specific spelling is compiler-dependent
- toggles both directives and conditional compilation

serial compilation may require stub library

generates threaded code and links against OpenMP run time



 Output for example program: Hello from1Hello from3Hello from0Hello from2

ordering will vary between runs (asynchronous execution)

Now: First exercise session





Simple work sharing, Scoping of Data, and Synchronization

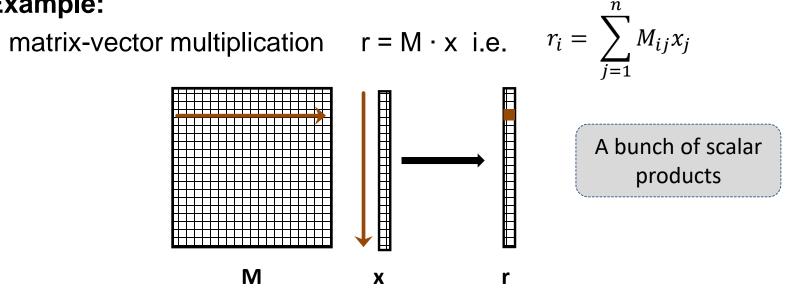




We know how to set up threading, but

- how can a large work item be divided up among threads? (using the API for this works in principle, but is tedious)
- what happens with objects that already exist before the parallel region starts?

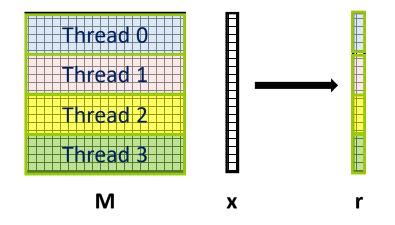
Example:







The idea is to split the work among threads



Note that

- all elements of x must be available to all threads
- Matrix-Vector is often deployed iteratively → r becomes x in the next iteration
 → copying of data must be possible

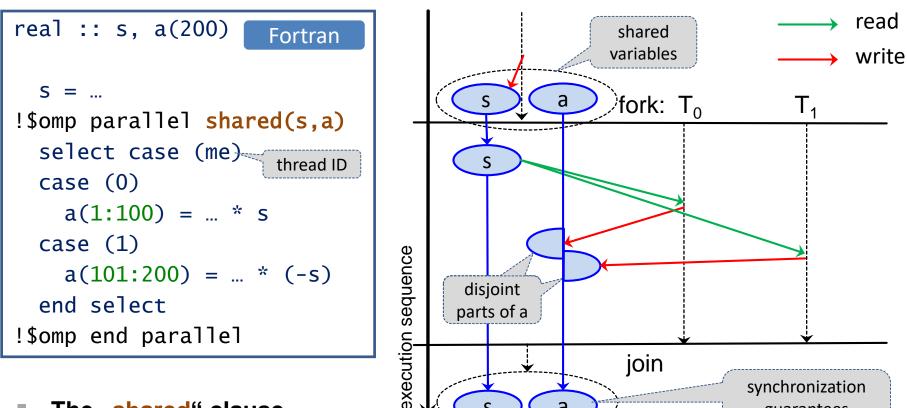
Consequence:

- need for variables that are accessible to all threads
 - \rightarrow "data sharing" is often a prerequisite for "work sharing"
 - \rightarrow a natural concept for a shared memory programming model



Sharing variables across threads





- The "shared" clause
 - implies that scalar **s** and array **a** both are accessible to all threads

Rules for concurrent accesses to a single object

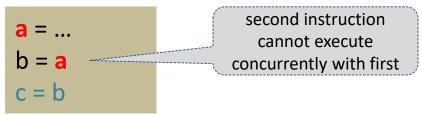
reads/writes or writes/writes by different threads are not permitted ("data races")

Note: updates to array a are OK because disjoint parts of object are updated

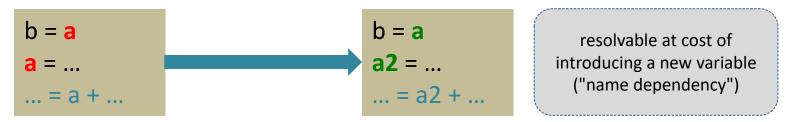
guarantees availability of **a** Data dependencies that prevent parallelization



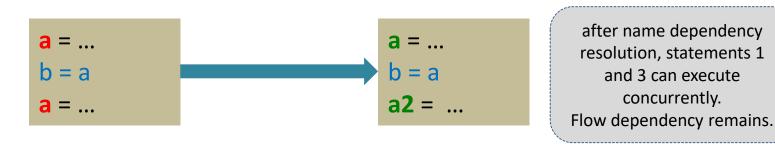
Flow dependency ("read after write", RAW):



Anti-dependency ("write after read", WAR):



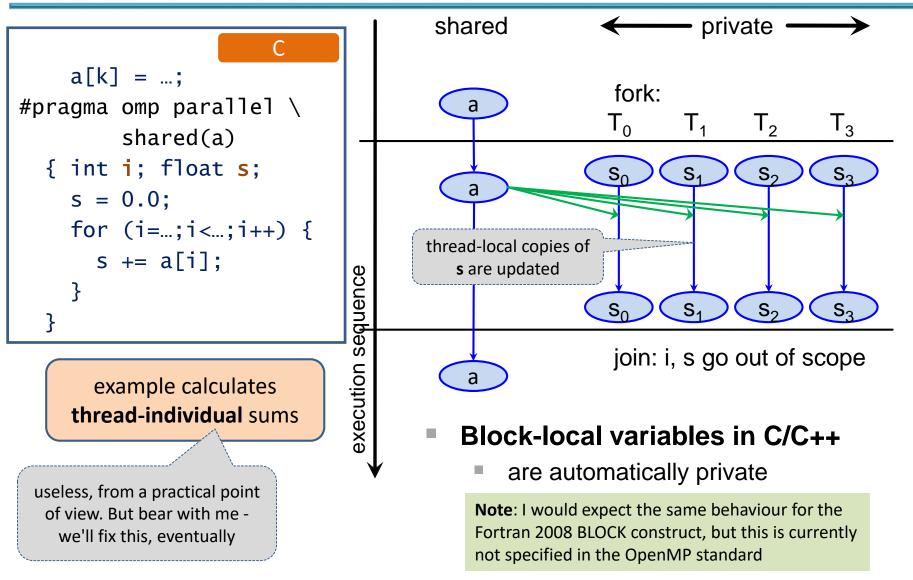
Output dependency ("write after write", WAW):





Privatization

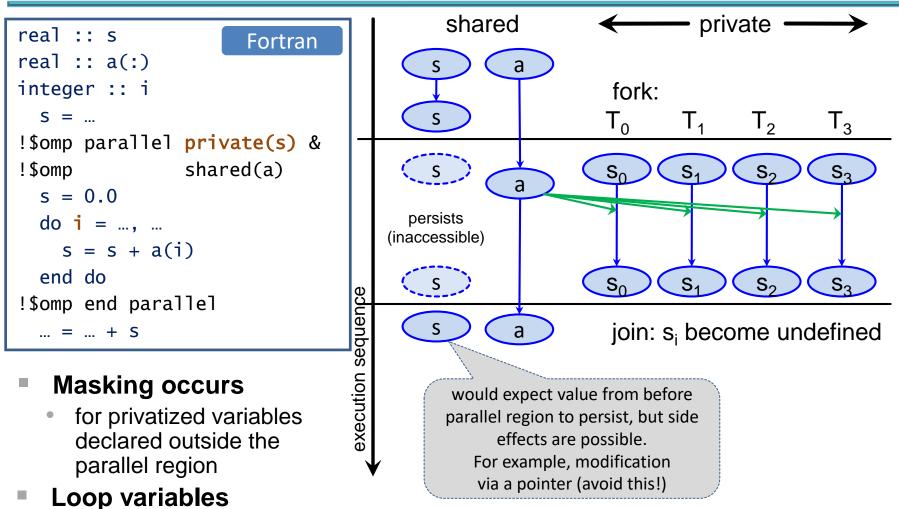






Privatization with masking





If **s** were shared, the program would have a race condition.

are always private



Code for work-shared Matrix-Vector multiplication: The DO / FOR directive



Serial Fortran	С
DO $k = 1$, n	for (k=0; k <n; k++)="" th="" {<=""></n;>
DO j = 1, n	for (j=0; j <n; j++)="" td="" {<=""></n;>
r(j) = r(j) + a(j, k) * x(k)	r[j] = r[j] + a[k*n+j] * x[k];
END DO	}
END DO	}
 OpenMP parallel 	#pragma omp parallel
!\$omp parallel	applies to j-loop
!\$omp do	#pragma omp for
DO $j = 1$, n	for (j=0; j <n; j++)="" td="" {<=""></n;>
DO $k = 1, n$	for (k=0; k <n; k++)="" td="" {<=""></n;>
r(j) = r(j) + a(j, k) * x(k)	r[j] = r[j] + a[k*n+j] * x[k];
END DO	}
END DO implicit barrier	
!\$omp end do all threads synchronize	}
= r()	= r[]; no race condition
!\$omp end parallel	} against previous
	definitions





Slicing of iteration space

- "loop scheduling"
- default behaviour is implementation dependent
- usually as equal as possible chunks of largest possible size, one chunk per thread

In the example,

- slicing is done as shown some slides earlier
- loop order was switched to avoid having many synchronizations

Additional clauses

 on both !\$OMP DO and !\$OMP END DO will be discussed in another talk

- Restrictions on loop structure
 - Trip count must be computable at entry to loop

• Disallowed:

C style loops modifying the loop variable in the loop body, or using a non-evaluable exit condition, or Fortran DO WHILE loop;

 loop body must be a well-formed structured block with single entry and single exit point

Note:

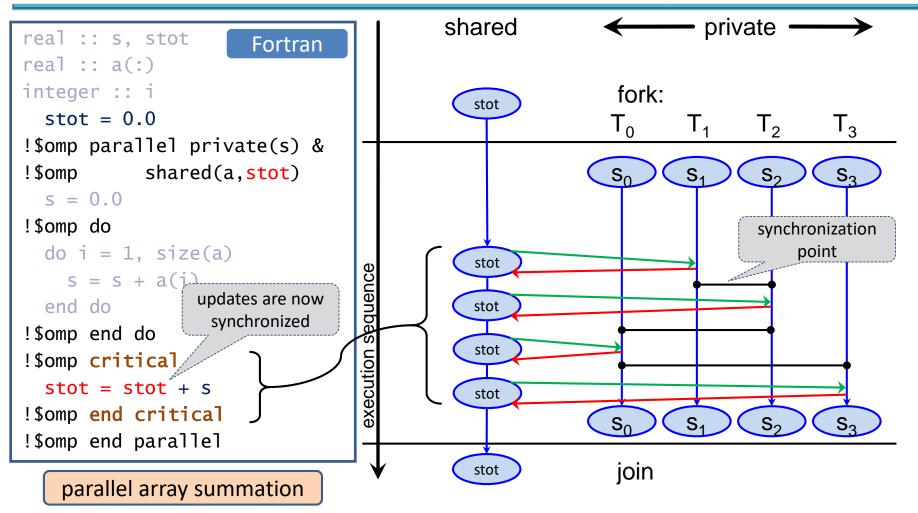
 directive (by default) acts only on outermost enclosed loop

actually, we're caught between a rock and a hard place here ...

Avoiding race conditions (1):

mutual exclusion via the critical directive



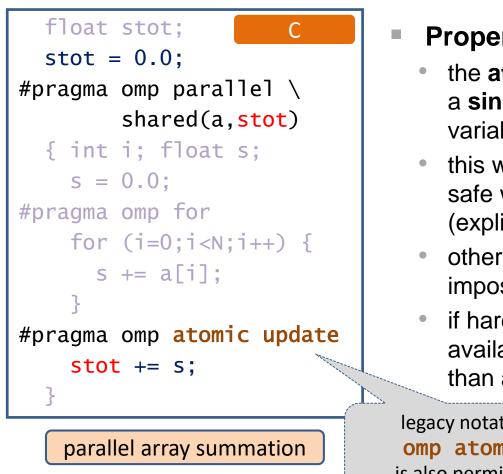


- Only one thread at a time can execute a critical region
 - others must wait → code in region is effectively serialized

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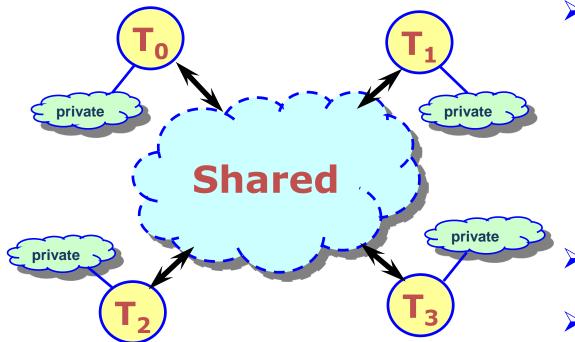
- **Properties of atomic operations**
 - the **atomic** directive applies only for a single update to a scalar shared variable of intrinsic type
 - this way of updating can be made safe when executed concurrently (explicit use of race condition!)
 - otherwise, no synchronising effect imposed by semantics
 - if hardware atomic instructions are available, likely to be more efficient than a critical region

legacy notation omp atomic is also permitted



The two kinds of memory in OpenMP

|--|



Data accessed by can be shared or private

- shared data one instance of an entity available to all threads (in principle)
- private data each perthread copy only available to thread that owns it
- Data transfer transparent to programmer

Synchronization

necessary for accessing shared data from different threads to avoid race conditions

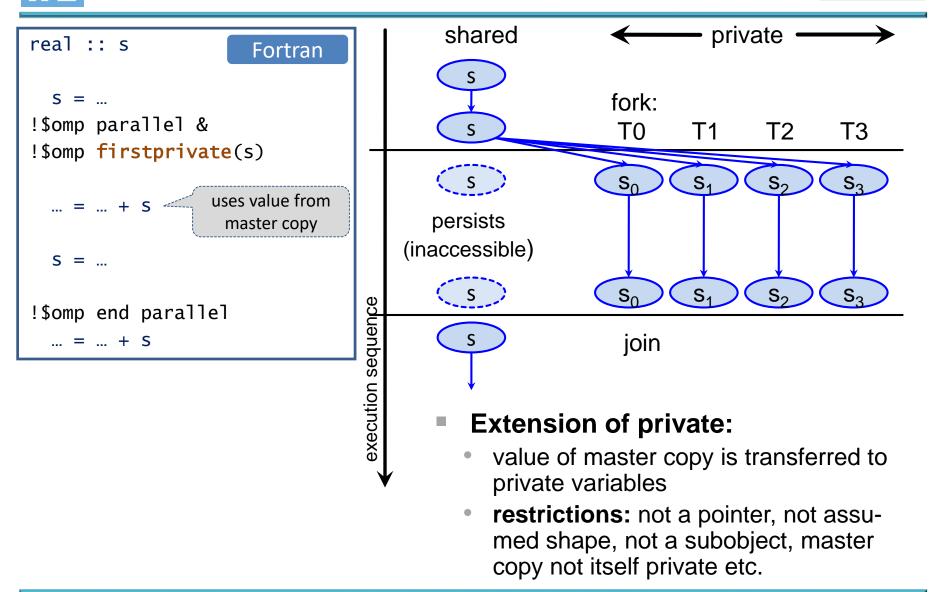
- implicit barrier
- explicit directive

now starting to wrap up ...

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The firstprivate clause

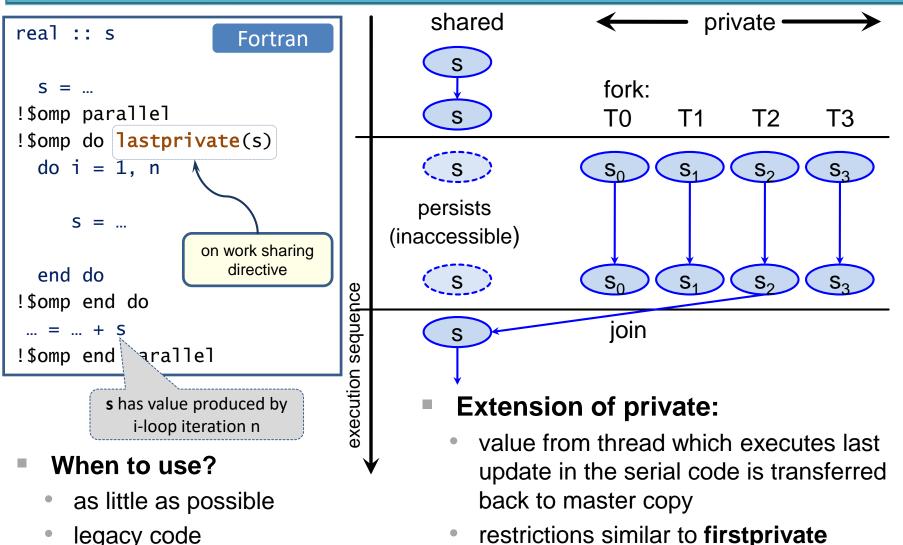






The lastprivate clause





legacy code





Scoping clauses can be specified for

- parallel regions
- loop work sharing constructs

Defaults

- apply if no clause is specified
- may vary by construct, but for the above the following apply:

pre-existing objects are by default **shared**, except for loop variables, which are **private**.

objects declared inside the lexical or dynamic scope of the construct are **private**.

this cannot be changed, of course

Recommendation:

 specify a default(none) clause on each directive that permits scoping: Fortran

!\$omp parallel default(none) &
!\$omp shared(...) private(...) ...

С

#pragma omp parallel default(none) \
 shared(...) private(...) ...

 this forces you to explicitly consider and specify scoping for all pre-existing objects

Now: Second exercise session

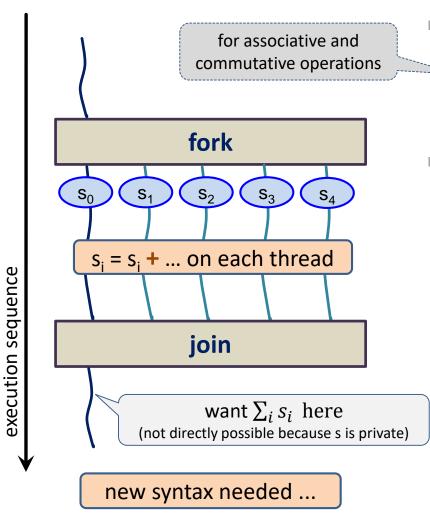




Reductions



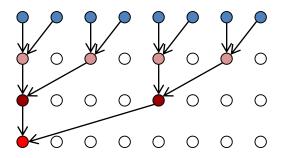




- Seen in previous exercise:
 - need for assembling partial results across threads
- up to now: with critical region

OpenMP reductions:

 sometimes more efficient implementation tunings like



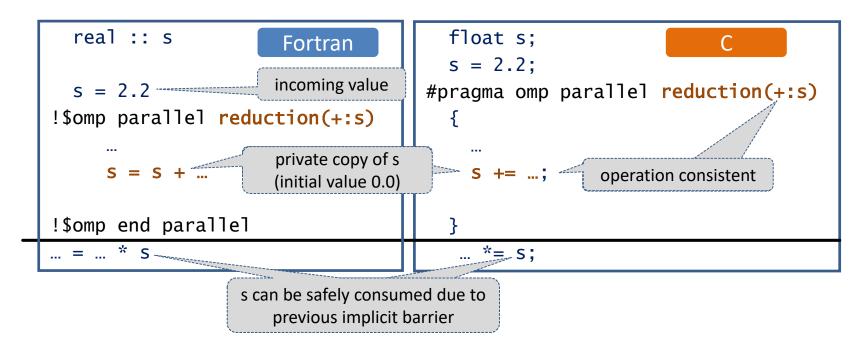
reduce complexity from $O(n_{threads})$ to $O(log_2(n_{threads}))$

 always easier to understand and maintain





Example 1: Sum reduction in a parallel region



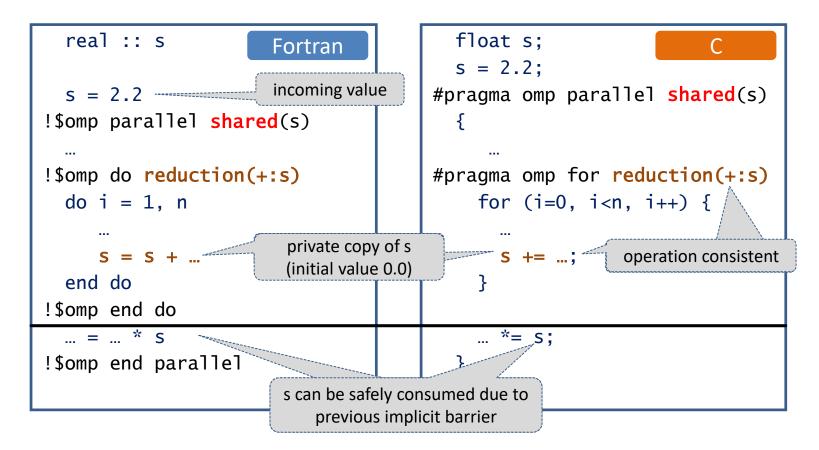
- value of s after end of parallel region: $s_{incoming} + \sum_i s_i$
- Note: multiple reductions are permitted

<pre>!\$omp parallel reduction(+:x,y,z)</pre>	!\$omp parallel	<pre>reduction(+:x,y) &</pre>
	!\$omp	<pre>reduction(*,z)</pre>





Example 2: Sum reduction in a work shared region



• value of s after end of worksharing region: $s_{\text{incoming}} + \sum_i s_i$





- Depends on operation
- Supported intrinsic operations:

Fortran

FOILIAII				
Operation	Initial value			
+	0			
-	0			
*	1			
.and.	.true.			
.or.	.false.			
.eqv.	.true.			
.neqv.	.false.			
MAX	-HUGE(X)			
MIN	HUGE(X)			
IAND	all bits set			
IEOR	all bits 0			
IOR	all bits 0			

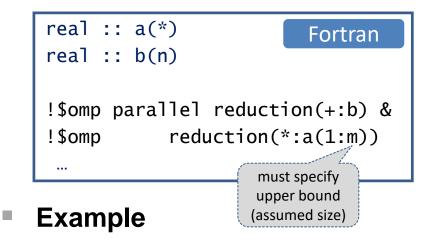




Operation	Initial value
+	0
-	0
*	1
&	0
1	0
٨	0
&&	1
	0
MAX	smallest representable value
MIN	largest representable value



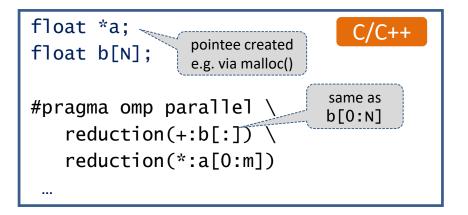




- reduces complete array b and m elements of array a, elementwise
- uses regular Fortran array section notation

[lower bound : upper bound]

General rules:



- C example does the same as the Fortran example
- OpenMP-defined sectioning syntax (differs from Fortran):

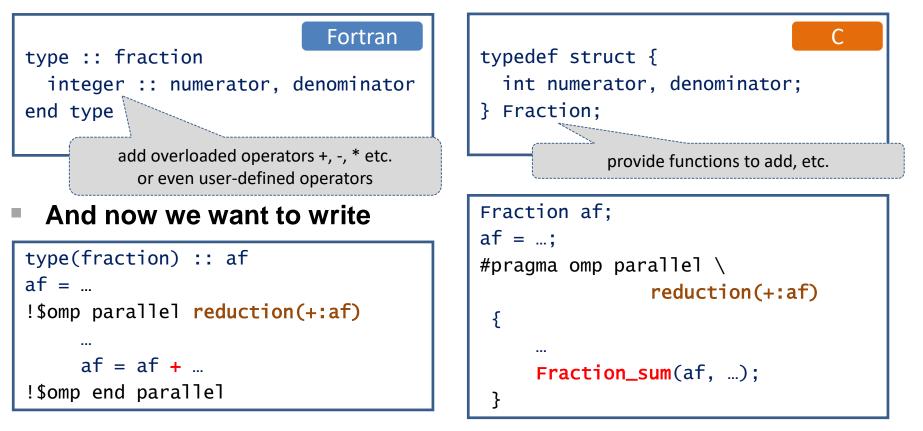
[lower bound : length]

- array section must be a **contiguous** object (\rightarrow no strides permitted)
- dynamic objects must be associated / allocated, and the status must not be modified for the private copies
 no deallocate/free within reduction region





Using derived types



 but the compiler will refuse to build it ("+" not known to OpenMP) unless further measures are taken ...



Fortran

 \cap

!\$omp declare reduction(+:fraction:omp_out=omp_out+omp_in) &
!\$omp initializer(omp_priv=fraction(0,1))

#pragma omp declare reduction(+:Fraction: \

Fraction_add(omp_out,omp_in)) \

initializer(omp_priv=Fraction{0,1})

Combiner

declare reduction(<op>:<type>:<combiner>)

connects to operator implementation
 Fortran: example defers to overloaded "+", C: references "Fraction_add" special OpenMP parameters omp_in, omp_out formally describe the two operands for each operation needed

Initializer

initializer(omp_priv=...) or initializer(function(...))

implements initial value setting for private copies
 Fortran: uses (overloaded) structure constructor, C similar special OpenMP parameter omp_priv formally describes private copy





More on Work Sharing

Loops and loop scheduling Collapsing loop nests Parallel sections





Default scheduling:

- implementation dependent
- typical: largest possible chunks of asequal-as-possible size ("static scheduling")

iteration space (threads color coded)

User-defined scheduling:

Fortran
static
!\$OMP do schedule(dynamic [,chunk])
guided

chunk: always a non-negative integer. If omitted, has a schedule dependent default value

- 1. Static scheduling
 - schedule(static,10)
 - 10 iterations
 - minimal overhead (precalculate work assignment)
 - default chunk value: see left

2. Dynamic scheduling

after a thread has completed a chunk, it is assigned a new one, until no chunks are left

schedule(dynamic, 10)

both threads take long to complete their chunk (workload imbalance)

- synchronization overhead
- default chunk value is 1





Size of chunks in dynamic schedule

- too small → large overhead
- too large \rightarrow load imbalance

Guided scheduling: dynamically vary chunk size.

- Size of each chunk is proportional to the number of unassigned iterations divided by the number of threads in the team, decreasing to chunk-size. (default: → 1)
- Chunk size:
 - means minimum chunk size (except perhaps final chunk)
 - default value is 1

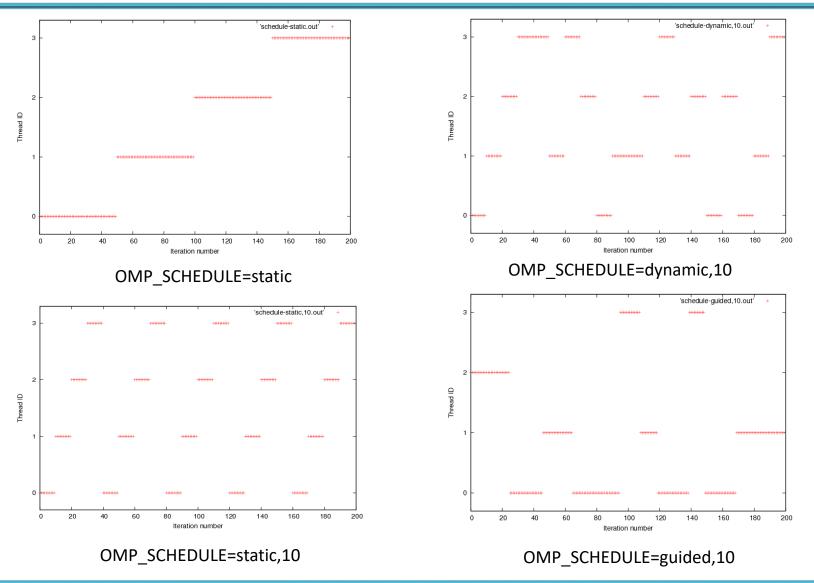


 both dynamic and guided scheduling are useful for handling poorly balanced and unpredictable workloads.



OpenMP Scheduling of simple for loops

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Decided at run time:

Fortranauto!\$OMP do schedule(runtime)

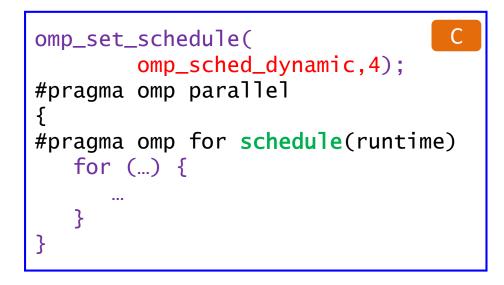
- auto (automatic scheduling)
 - programmer gives implementation the freedom to use any possible mapping.

runtime

- schedule is one of the above or the previous two slides
- determine by either setting OMP_SCHEDULE, and/or calling omp_set_schedule() (overrides env. setting)
- find which is active by calling omp_get_schedule()

Examples:

- environment setting: export OMP_SCHEDULE='guided' export OMP_NUM_THREADS=4 ./myprog.exe
- call to API routine:



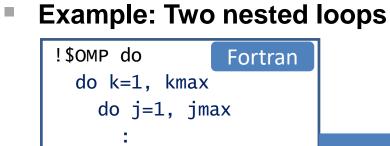


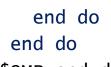


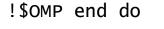
- Please check your compiler documentation for implementationdependent aspects
- An implementation may add its own scheduling algorithms
 - code using specific scheduling may be at a disadvantage
 - recommendation: Allow changing of schedule during execution
- If runtime scheduling is chosen and OMP_SCHEDULE is not set
 - execution starts with implementation-defined setting









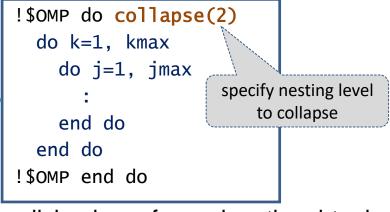


- assume kmax is 2, and jmax is 3
- then the workshared loop will scale to at most 2 threads

Therapy:

- use a collapse clause to improve scaling
- this flattens two (or more) loop nests into a single iteration space





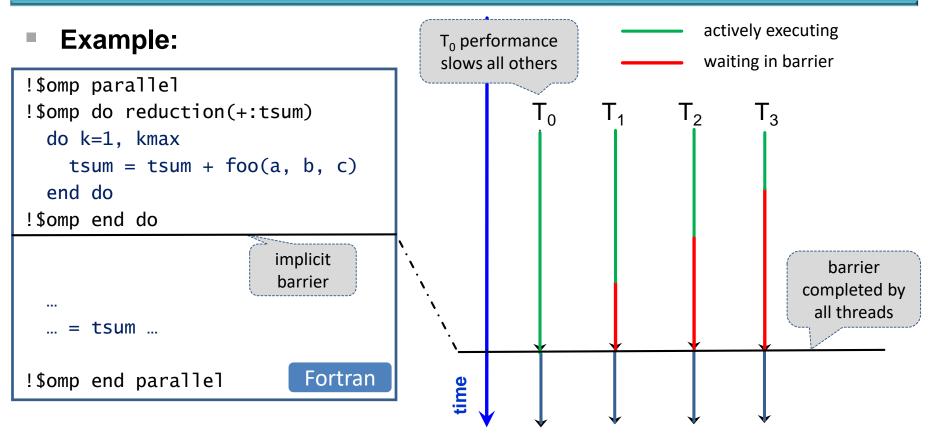
slicing is performed on the virtual index I_{coll}:

I _{coll}	0	1	2	3	4	5	sequenced by
J	1	2	3	1	2	3	serial execution
K	1	1	1	2	2	2	order

- Restrictions:
 - rectangular iteration space
 - CYCLE/continue in innermost loop only





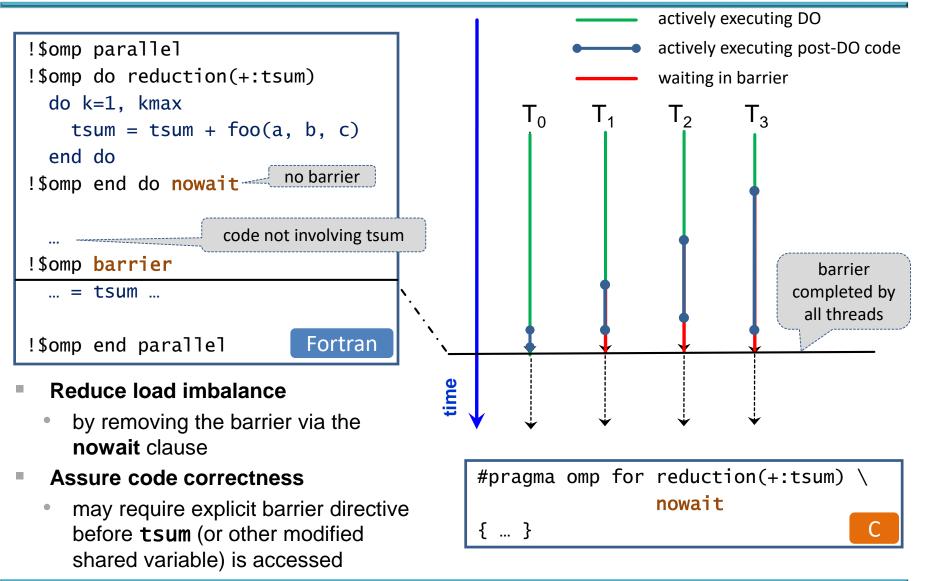


- Assumptions on code following the synchronization point:
 - does not involve tsum
 - has a load imbalance that is inverse to that of preceding code block



nowait clause and explicit barrier directive



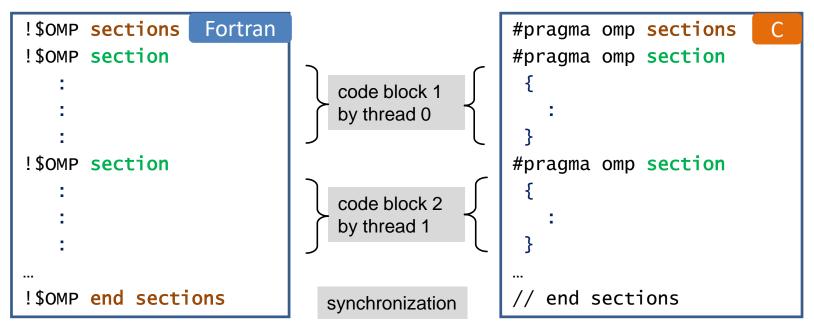






Non-iterative work-sharing construct

• distribute a static set of structured blocks



- each block is executed exactly once by one of the threads in the team
- Allowed clauses on sections:
 - private, first/lastprivate, reduction, nowait





Restrictions:

- section directive must be within lexical scope of sections directive, and directly enclosed (no interleaved language construct is permitted)
- sections directive binds to innermost enclosing parallel region

 → only the threads executing the binding parallel region participate in the
 execution of the section blocks and the implicit barrier (if not eliminated with
 nowait)

Scheduling to threads

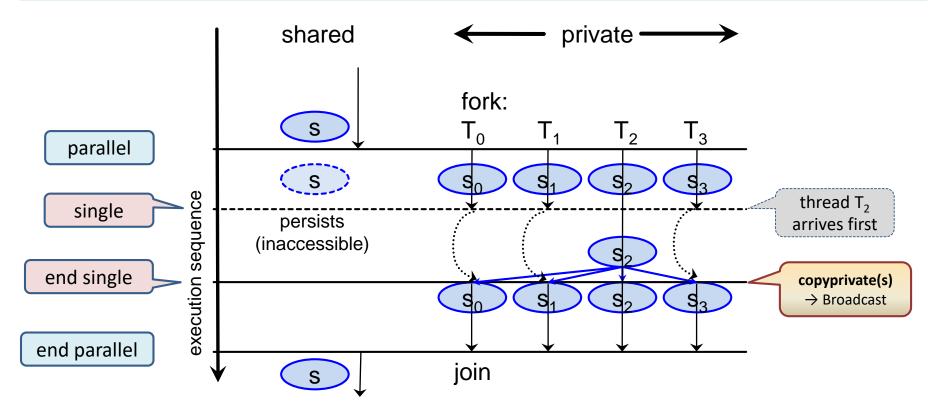
- implementation-dependent
- if there are more threads than code blocks, excess threads wait at synchronization point

In modern OpenMP,

 tasking provides a much more flexible and scalable way to implement this and much more general patterns → will be treated tomorrow

single directive and copyprivate clause





Execution:

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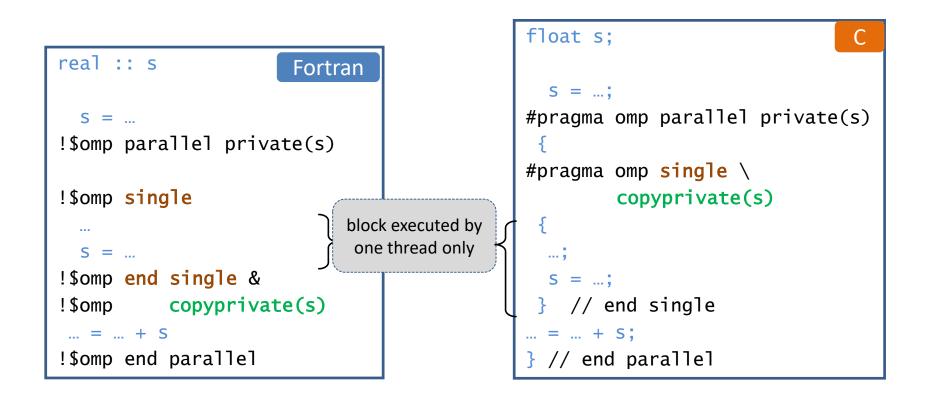
- only one thread of the team executes the statements in the block
- others go to the end of the block

Synchronization

 of all threads at end of single block







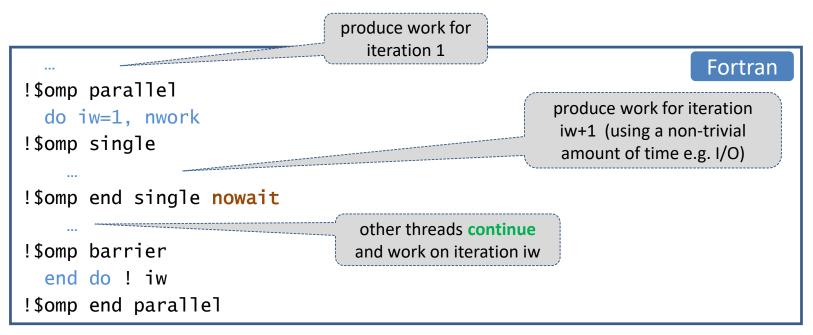
Note:

 update of shared variables inside a single block is safe against subsequent accesses, due to synchronization at the end of that block





- Implement a self-written work scheduler
 - one possible scheme (of many ...), sketched only:



not the most efficient method

 \rightarrow preferably use tasking (covered tomorrow); the single construct will be relevant in this context

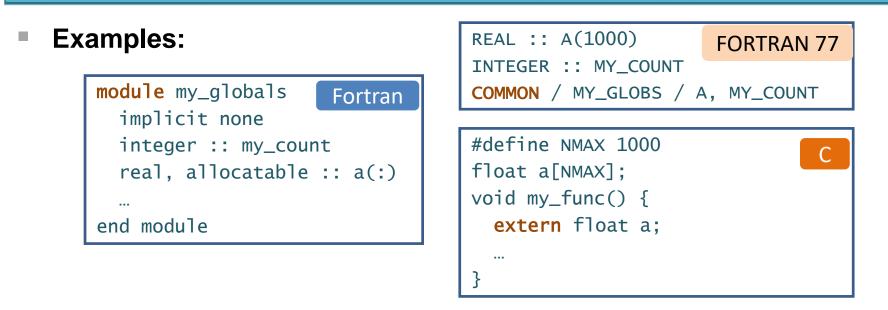




Global variables and threading







- Such variables by default have shared scope
- The same applies for variables with the SAVE (Fortran) or static (C) attribute
- A Implication:
 - code using such memory is often not thread-safe, unless mutual exclusion is used for accessing the objects





- When program semantics requires that each thread work on its own copy, privatization is necessary
 - not exactly the same as private variables \rightarrow separate syntax needed
- **C**:
 - #pragma omp threadprivate(list)
 - list is a comma-separated list of file-scope, namespace-scope, or static block-scope variables that do not have incomplete types

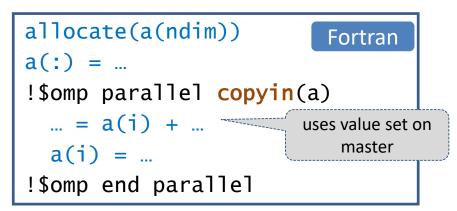
Fortran:

- !\$omp threadprivate(list)
- list is a comma-separated list of named variables and named common blocks. Common block names must appear between slashes.
- Objects start out with master copy existing only
 - thread-private copies (with undefined values) spring into existence when the first parallel region is started



Copyin clause

- broadcasts object values from master copy to threadindividual copies
- works analogous to the firstprivate clause



Recommendations:

- Avoid using global variables in the context of threading
- Use object-based design instead

- Subsequent parallel regions:
 - thread-individual copies retain their values (by thread) if
 - second parallel region not nested inside first
 - 2. same number of threads is used
 - 3. no dynamic threading is used

Note: none of the potential violations of the above three rules are dealt with in this course





... useful varia





Fortran	С
!\$omp master	#pragma omp master
block	<pre>{ block }</pre>
!\$omp end master	

Only thread zero (from the current team) executes the enclosed code block

 there is no implied barrier either on entry to, or exit from, the master construct. Other threads continue without synchronization

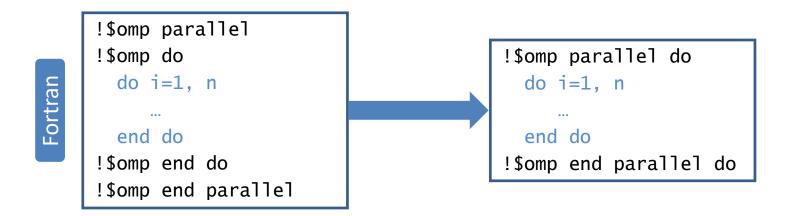
Notes:

- Not all threads must reach the construct; if the master thread does not reach it, it will not be executed at all
- this is not a work sharing construct, it only serves for execution control





- Certain combinations of constructs can be fused
 - the result is a single construct that behaves as if the two individual ones were tightly nested
 - may be more efficient due to reduced synchronization needs
 - is often easier to read
- Example: joint "parallel do" (C has "parallel for" here ...)

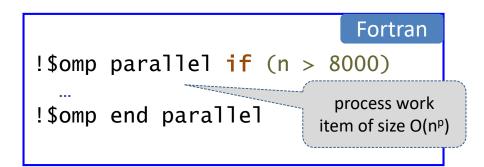


• both variants have the same semantics





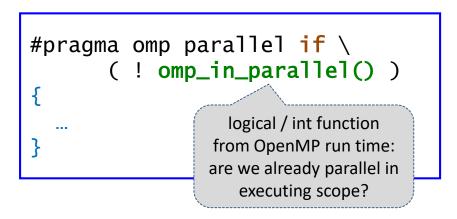
Put an "if" clause on a parallel region



- specify a scalar logical argument
- may require manual tuning for properly dealing with thread count dependency etc.

• Specific uses:

- execute serially for small problem sizes (parallel overhead may kill performance)
- 2. suppress nested parallelism in a library routine:



Now: Third exercise session





OpenMP 4.0 SIMD (vectorization) directives

Optimization of innermost loop structures

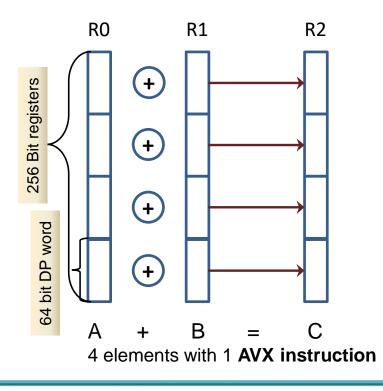
Acknowledgment due to M. Klemm (Intel)





Example:

- Sandy Bridge vector unit
- 256 Bit SIMD
- addition of 8 Byte words



Instruction capability

 1 vector add and 1 vector mult per cycle → theoretical Peak 8 Flops/cycle (double precision)

LD/ST issue capability for Sandy Bridge

- 4 Words LD/cycle
- 4 Words ST/(2 cycles)
- performance boost depends on algorithm, including its temporal locality properties

 More recent processors may have more advanced units

- more SIMD lanes
- additional vector operations





- minimize in the image of the
 - or use non-portable extensions
 - > programming models (e.g. Intel Cilk Plus)
 - > intrinsics (e.g. _mm_add_pd())
 - > compiler pragmas

```
#pragma omp parallel for
#pragma vector always
#pragma ivdep
for (int i=0; i<N; i++) {
   a[i] = b[i] + ...;
}</pre>
```

which may or may not get ignored by the compiler

C





Vectorize a loop nest

- cut into chunks that fit into a SIMD vector register
- without parallelization of the loop body

Syntax

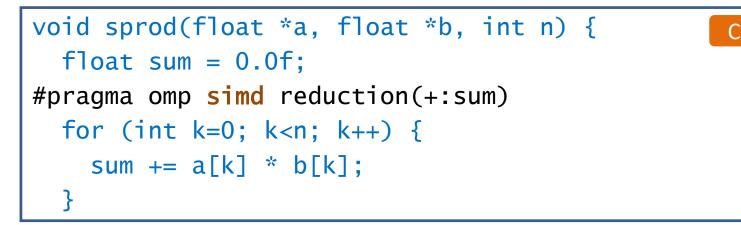
#pragma omp simd [clause[[,] clause], ...]
for loops

!\$omp simd	<pre>[clause[[,] clause],]</pre>	
do 1oops		
[!\$omp end	simd]	Fortran

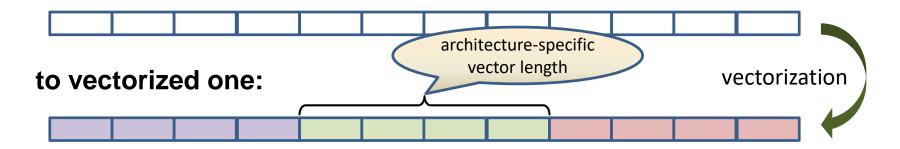




Scalar product



Converts serial element-wise execution







- Existing ones adapted to SIMD-style execution
 - required for more complex loop bodies
- private (var-list)



create uninitialized vectors for variables in var-list (loop iteration variables are private by default)

lastprivate (var-list)

copy last iteration value to variable at the end of the construct

reduction (op:var-list)

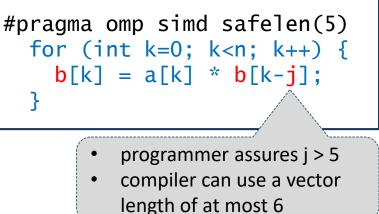
create private copies for variables in var-list and apply the reduction operation *op* at the end of the construct





safelen (length)

 maximum distance between iterations that can run concurrently without breaking any dependencies



- linear (list[:linear-step])
 - produce private copy of a variable that is in linear relationship with the loop iteration variable: $x_i = x_{start} + (i i_{start}) *$ linear-step





aligned (list[:alignment])

specifies that variables in the list are aligned, either by the specified integer value of alignment in units of bytes, or in implementationspecific manner

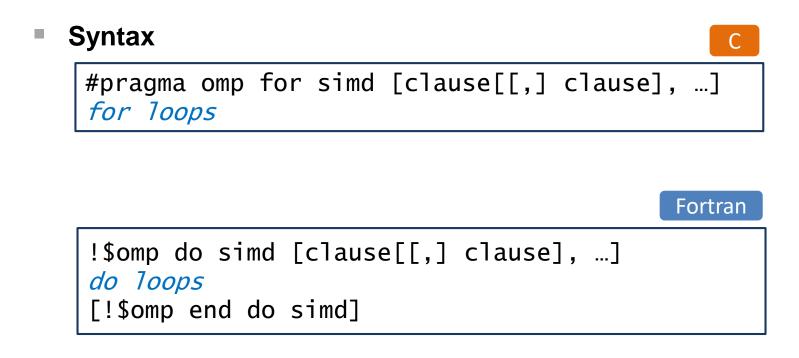
collapse(n)

collapse iteration space of a SIMD loop nest



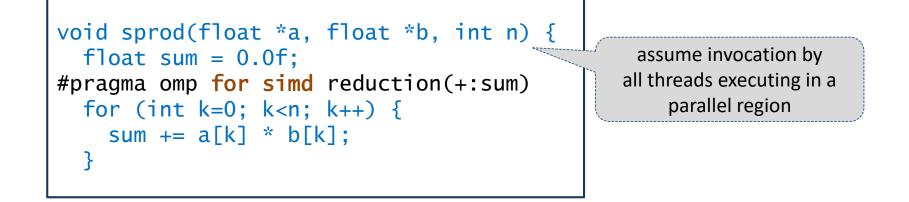


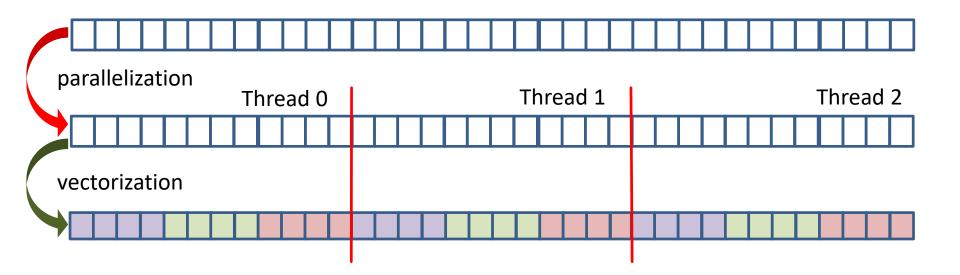
- Parallelize and vectorize a loop nest
 - distribute iteration space of loops across threads
 - subdivide loop chunks to be processed in SIMD registers





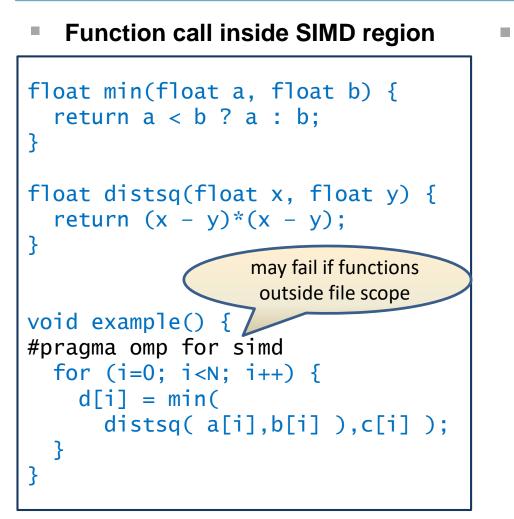












- Therapy: explicitly declare for use in vectorized loops
 - C/C++ syntax

#pragma omp declare simd
function def. or dec1.

Fortran syntax

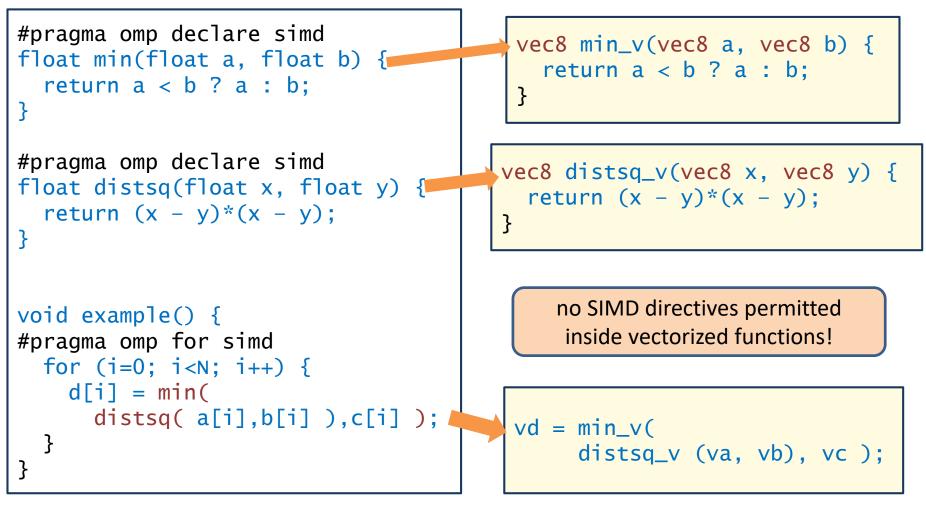
!\$omp declare simd &
!\$omp (proc-name-list)

- clauses are also supported
- causes generation of multiversion code by the compiler





vectorized versions of generated functions are shown





simdlen (length)

generate function to support supplied vector length

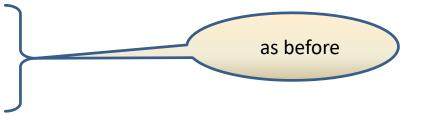
uniform (argument-list)

argument has a constant value between iterations of invoking loop

inbranch vs. notinbranch

function always / never called from inside an if statement

- linear (list[:linear-step])
- aligned (list[:alignment])
- reduction (op:var-list)







- Case studies on vectorizable applications:
 - show performance improvements of factor 1.5 4.3 compared to auto-vectorized code
 - you may not be as successful, but a 20% performance improvement for 45 min optimization work is also quite nice

Resolution of dependencies

- may sometimes involve code restructuring and splitting of loops
- Further features available: combination of device control directives with SIMD
 - not discussed in this talk

Now: Fourth exercise session



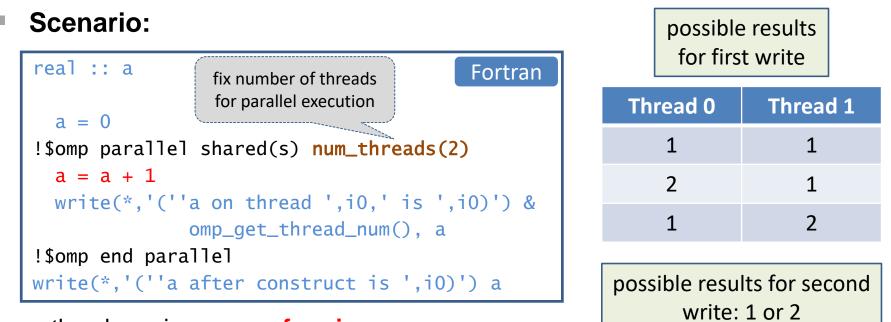


More on Synchronization and Correctness

Memory model Identifying correctness problems Named critical regions Atomic operations Mutual exclusion with locks







- the above is non-conforming
- data race causes unpredictable results to be produced
- Reason:
 - different threads can have different views on same variable: temporary view (in-register value) vs. memory value
 - these two views become inconsistent when a thread modifies the variable





Flush Operation

- is performed on a set of (shared) variables or on the whole threadvisible data state of a program
- discards temporary view:

→ modified values are forced to cache/memory (requires exclusive ownership)

→ next read access must be from cache/memory

 further memory operations only allowed after all involved threads complete flush:

→ restrictions on memory instruction reordering (by compiler)

> recommend to avoid use of explicit flushes

Ensure consistent view of memory:

- Assumption: want to write a data item with one thread, read it with another one
- Order of execution required:
- 1. thread A writes to shared variable
- 2. thread A flushes variable
- 3. thread B flushes same variable
- 4. thread B reads variable
 - The challenge is to assure step 3 happens after step 2
- OpenMP synchronization semantics assure this as well as the necessary flush operations (if correctly used)

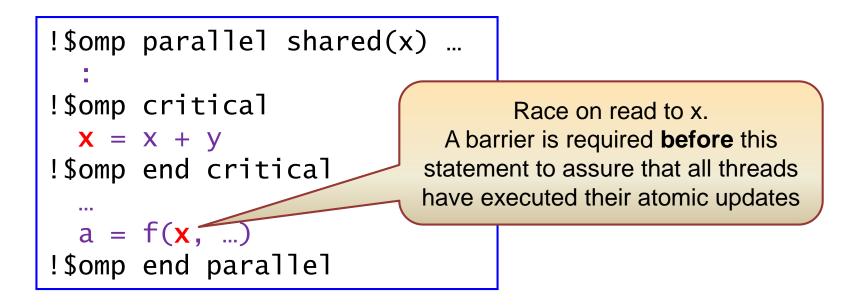
!\$omp flush [list]





Example: update via critical region

- mutual exclusion is only assured for the statements inside the block i.e., subsequent threads executing the block are synchronized against each other
- If other statements access the shared variable, you may be in trouble:





OpenMP correctness analysis:

- no special compiler option needed (except perhaps –g)
- GUI also for Linux-based system

Identify memory issues in addition to threading issues

• leaks, dangling pointers etc.

Start up GUI

- prerequisites: set up environment and possibly stack limit
- then, invoke the GUI with

inspxe-gui &

 command line inspxe-cl is also available, but will not be discussed in this talk





<u>F</u> ile View Help		
Welcome 💌		
Project name: Location:	Race_1 0 0	enter project name then press "create project"
	Create Project Current project: heat_tune1	Cancel
	 Threading Error Analysis / Detect Deadlocks and Data Races Threading Error Analysis / Locate Deadlocks and Data Races Memory Error Analysis / Detect Leaks Memory Error Analysis / Locate Memory Problems New Analysis 	Mew Project
	Recent Projects: > <u>tasked_integral_c</u> > <u>tasked_integral</u> > <u>demo_kurs</u> > fp	r004ti3 [heat_tune1] r003ti3 [heat_tune1] r002ti3 [heat_tune1] r001ti3 [heat_tune1] r000ti3 [heat_tune1]



Configure the project



	race_sections - Project Properties	
Target Suppressions Search Direct	tories	
Launch Application	Launch Application Specify and configure application you want to analyze. Press F1 for more details.	
	Application: //home/cluster/pr28fa/a2832ba/Kurse/courses/openmp/threading_	to V Browse
	Application parameters:	✓ Modify
	Working directory: //home/cluster/pr28fa/a2832ba/Kurse/courses/openmp/threading_	to V Browse
	Inherit system environment variables User-defined environment variables:	
		Modify
	Store result in the project directory: //home/cluster/pr28fa/a2832ba/intel/inspxe/Projects/race_sections	
	Store result in (and create link file to) another directory	
	/home/cluster/pr28fa/a2832 ba/intel/inspxe/Projects/race_sections	
	Result location: /home/cluster/pr28fa/a2832ba/intel/inspxe/Projects/race_sections/r@@@{at}	
	Advanced	
	Child application:	
	Suppression mode: Delete problems	
	Exclude modules:	Modify
		OK Cancel

Needed information:

- executable name (must have been built with OpenMP)
- executable path (autocompleted)
- arguments if needed by executable
- Further advanced settings are possible



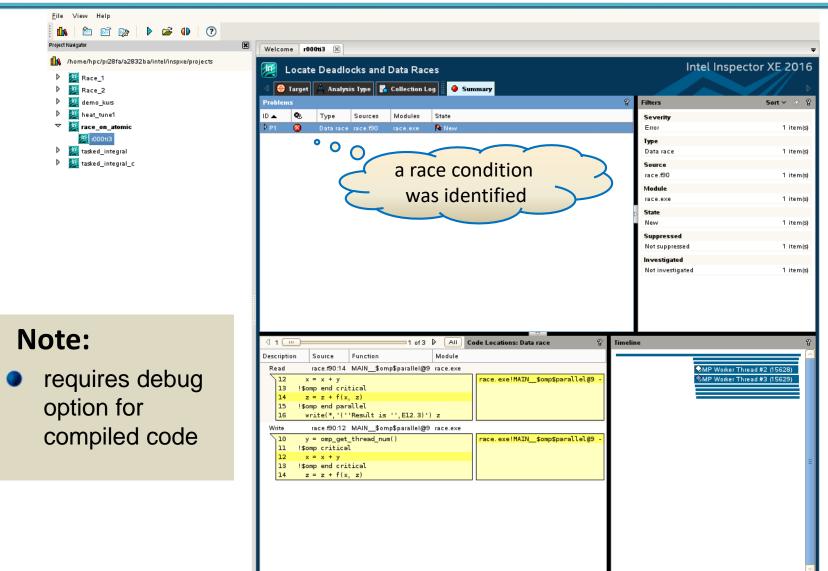


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Welcome 1000til New Inspector Re	sult 🕱	₹
💆 Configure Analysis Type		Intel Inspector XE 2013
🖞 🙏 Analysis Type		
Threading Error Analysis	10x40x Detect Deadlocks 20x80x Detect Deadlocks and Data Races 0x10x160x Detect Deadlocks and Data Races Analysis Time Overhead Detect Deadlocks and Data Races Cacate Deadlocks and Data Races Widest scope threading error analysis type. Maximizes the load on the system and the time however, detects the widest set of errors and provides context and maximum detail for those Terminate on deadlock Stack frame depth: 16 Normal ✓	
	 Analyze without debugger Analyze without debugger Run an analysis and report all detected problems. Use to view correctness issue examine them. Enable debugger when problem detected Run an analysis under the debugger and stop every time a problem is detected problem detected. Not recommended when running a threading analysis beca Select analysis start location with debugger Run target application under the debugger with analysis disabled until you che the application under the debugger with analysis command to turn on analysis reach a problem of interest. O tealis 	 Select analysis mode, then start here: Threading Error Analysis → locate deadlocks and data races note potentially high performance impact
	Detect deadlocks: Yes Terminate on deadlock: No Detect lock hierarchy violations: Yes Save stack on lock creation: Yes Cross-thread stack access detection: Hide problems/Show warnings	Project Properties



Error indication by severity

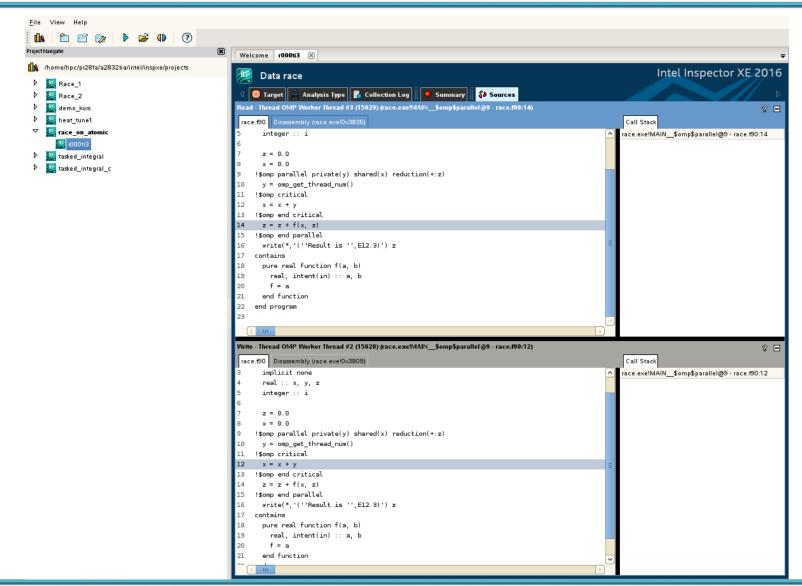






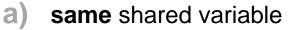
Source window: conflicting reads/writes

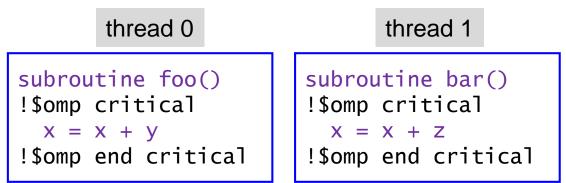




Critical regions: consider multiple updates







critical region is global \rightarrow OK

b) different shared variables

<pre>subroutine foo() !\$omp critical</pre>	<pre>subroutine bar() !\$omp critical</pre>
<pre>x = x + y !\$omp end critical</pre>	<pre>w = w + z !\$omp end critical</pre>

mutual exclusion not required \rightarrow unnecessary loss of performance

Fortran

Fortran



Fortran



- Solution:
 - use a named critical

subrout !\$omp o	tine foo() critical <mark>(foo_x)</mark>	<pre>subroutine bar() !\$omp critical (foo_w)</pre>
x = > !\$omp e	< + y end critical <mark>(foo_x)</mark>	<pre>w = w + z !\$omp end critical (foo_w)</pre>

mutual exclusion only if same name is used for critical regions acting on different code blocks

Note: The atomic directive is bound to the updated variable

 \rightarrow problem does not occur when such a directive is used.





Assumption:

- v, w private or shared scalar variables
- x a shared scalar variable
- Atomic read:

#pragma omp atomic read
v = x;

Atomic write:

```
#pragma omp atomic write
x = v;
```

Atomic capture

- !\$omp atomic capture
 v = x
 x = x <op> w
 !\$omp end atomic
- different ordering of statements also allowed

Not atomic:

- evaluation of expressions or updates on v
- Atomic update:
 - !\$omp atomic update
 - same as "traditional" atomic directive



Atomic directives

 permit the programmer to explicitly program with race conditions

Rationale for use:

- performance
- tailored synchronizations → will usually require explicit flush operations (not discussed)

Programmer's responsibility

- to assure that no inconsistencies result → must evaluate results from all possible interleavings of execution by different threads
- tools might not be able to observe problems

Synchronization effect

- apart from the value change on the variable itself being visible, no synchronization is done
- sequentially consistent atomic operations:

#pragma omp atomic \
 seq_cst update
 x = x + v;

perform a flush on all threadvisible variables (but no synchronization otherwise). Semantics are the same as for such operations in the C++11 standard

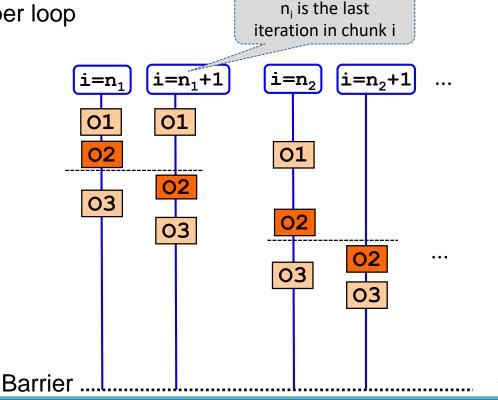




Statements must be within body of a loop

- threads do work with statements in O2 ordered as in sequential execution
- requires ordered clause on enclosing loop worksharing directive
- only effective if code is executed in parallel
- only one ordered region per loop
- Execution scheme:

```
!$OMP do ordered
do I=1,N
        01
!$OMP ordered
        02
!$OMP end ordered
        03
end do
!$OMP end do
```



Execution sequence





Loop contains recursion

- dependency requires serialization
- only small part of loop (otherwise performance issue)

Loop contains I/O

 it is desired that content of output (file) be consistent with serial execution

```
#pragma omp for ordered
for (i=1;i<n;i+) {
    ... // large block
#pragma omp ordered
    { a(i) = a(i-1)+...; }
} // end loop</pre>
```

```
!$OMP do ordered
do I=1,N
... ! calculate a(:,I)
!$OMP ordered
write(unit, ...) a(:,I)
!$OMP end ordered
end do
!$OMP end do
```

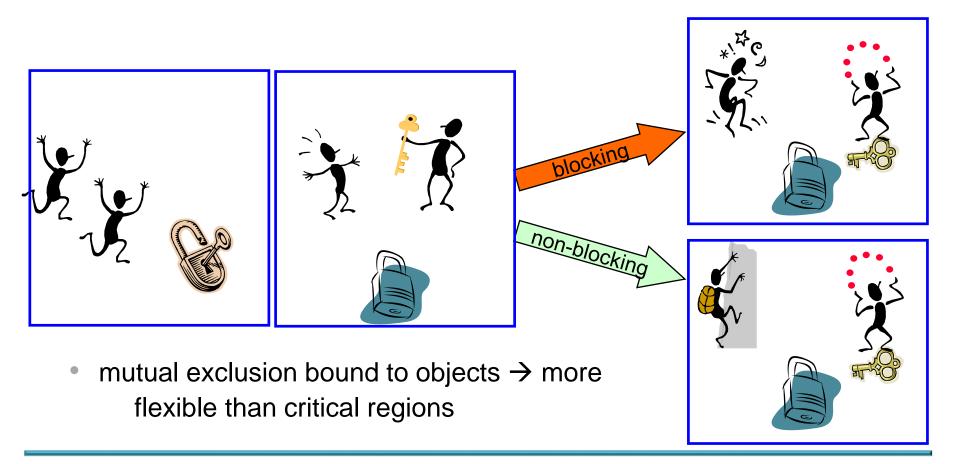


C





A shared lock variable can be used to implement specifically designed synchronization mechanisms







- Two variants of locks exist:
 - simple locks
 - nestable locks (will not be dealt with in detail in this course)
- Declaration of a lock variable

```
use omp_lib typically an integer capable of
representing an adress
...
integer(omp_lock_kind) :: a_lock
integer(omp_nest_lock_kind) :: a_nestable_lock
#include <omp.h> C
...
omp_lock_t a_lock;
omp_nest_lock_t a_nestable_lock;
```





- The initial state of a lock variable is "uninitialized"
 - i.e. it is not actually associated with a lock variable
- Need to invoke an initialization function on it before it is used
 - subroutines / void functions provided in OpenMP run time

Name	Purpose
<pre>omp_init_lock(omp_lock_t *lock)</pre>	initializes an uninitialized lock; the lock variable has the state "unlocked" on return
<pre>omp_destroy_lock(omp_lock_t *lock)</pre>	destroys a lock that has the state "unlocked".
<pre>omp_init_nest_lock (omp_nest_lock_t *lock)</pre>	initializes an uninitialized nestable lock; the lock variable has the state "unlocked" on return, and its nesting count is zero.
<pre>omp_destroy_nest_lock (omp_nest_lock_t *lock)</pre>	destroys a nested lock that has the state "unlocked".

• Fortran: replace *lock argument by integer of appropriate kind





- An initialized OpenMP lock can be in one of the states unlocked, or locked
- The (unique) thread that has successfully acquired the lock is said to own the lock
- Only the thread that owns the lock can release it, returning it to the unlocked stage.

Name	Purpose
<pre>omp_set_lock(omp_lock_t *lock)</pre>	If the lock is already locked by another thread, block until the state of the lock changes. If the lock is in the state unlocked, acquire it, setting it to the locked state, and continue execution.
<pre>omp_unset_lock(omp_lock_t *lock)</pre>	Release the lock that is owned by the executing thread.

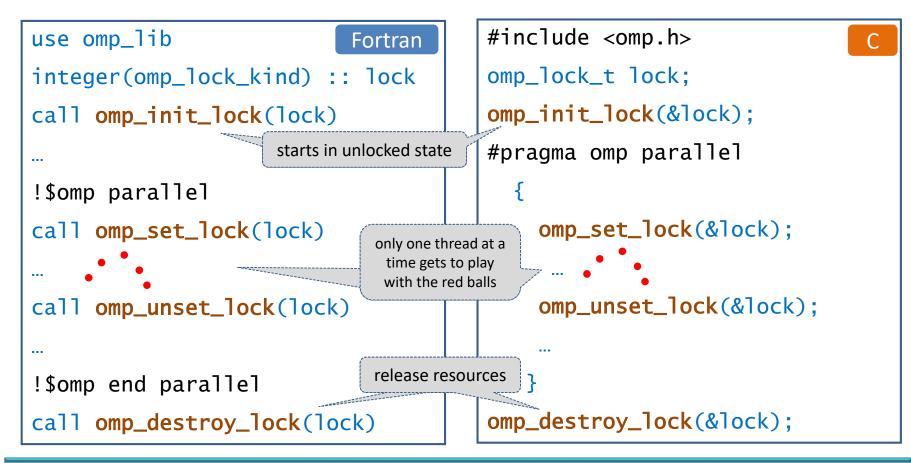
Notes:

- state combinations not described in the table are not permitted (e.g., a thread trying to unset a lock it does not own)
- the lock variable must be shared in the calling scope





- Usage pattern analogous to named critical region
 - programmer is responsible for relationship between lock and objects protected by it







Fortran

С

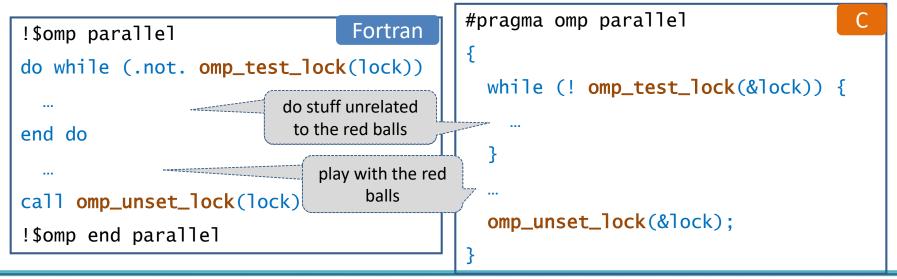
Function call signature

logical function omp_test_lock(lock)

int omp_test_lock(omp_lock_t *lock)

- if the lock is already locked by another thread, return "false"
- if the lock has the state unlocked, acquire it (setting the state to locked) and return the value "true".

Permits implementing additional concurrency







Potential performance issues

- locks are a relatively expensive synchronization mechanism
- lock contention (algorithm dependent)
- Programming issues
 - easy to produce deadlock (non-composable against other constructs)
- Nestable locks
 - extended semantics for repeated locking (additional nesting count)

Locks with hints (OpenMP 4.5)

- programmer can specify expected usage pattern, but the actual effect is implementation dependent
- this is an advanced topic, and success may require special hardware features (transactional processing)





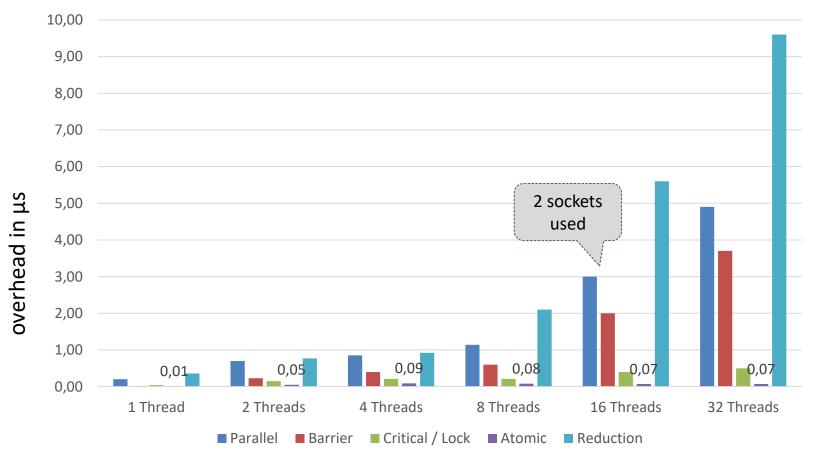
Syncbench from the EPCC OpenMP microbenchmarks is used

- evaluates the overheads for all synchronizing constructs systematically
- overhead is what remains even if no workload is processed
- Showing results as a function of thread count
 - alternatively, depending on node architecture and used compiler
- Note order of magnitude
 - a microsecond typically corresponds to a couple of thousand CPU cycles





Westmere 4-socket node overhead with ICC 15







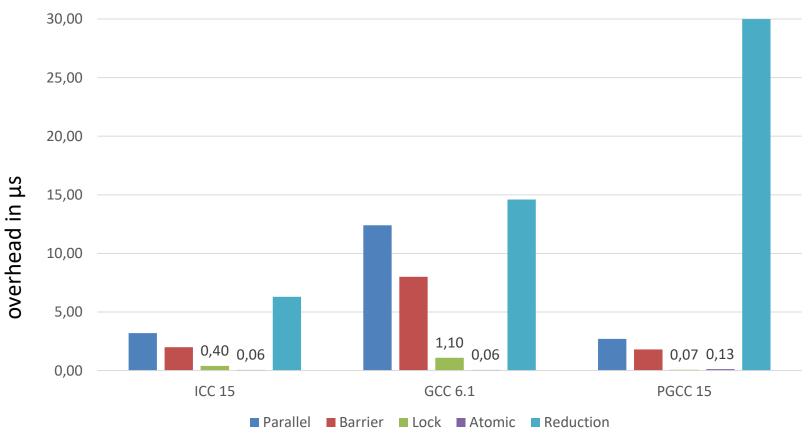








Westmere 20 thread results





- Therapy 1:
 - use the right compiler
 - **note:** x86 does not (yet) support hardware synchronization
- Therapy 2:
 - execute serially for small problem sizes
 - conclude parallel execution if not needed any more
- Therapy 3 (may be most effective):
 - reduce the synchronization requirements of your algorithm
 - Examples: nowait clause, or extend parallel regions to reduce number of forks/joins





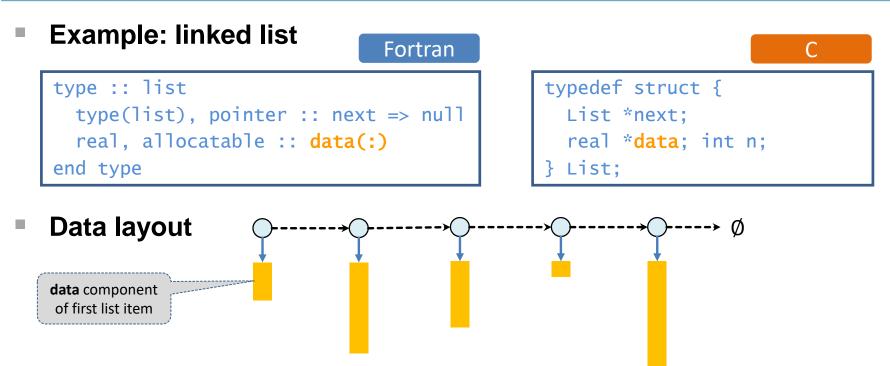
Tasking

Work sharing for irregular problems, recursive problems and information structures

Acknowledgement due to L. Meadows/T. Mattson (Intel) for their SC08 slides



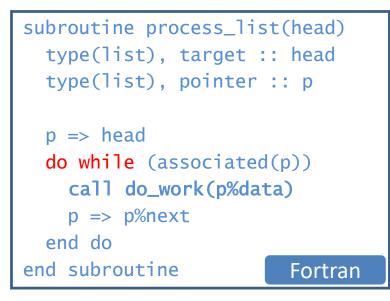


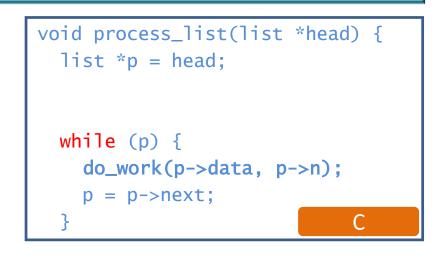


- each list item may carry a different payload
- parallel processing on a per-list-item basis → load imbalance is likely to occur
- the list as a whole is intended to be shared (i.e. no copies of payload should be created during processing)









- Not a regular loop in the sense of OpenMP
 - cannot use work sharing constructs even though potential concurrency is obvious.
- In general:
 - API calls for processing information structures often are recursively invoked → OpenMP 2.5 offers no means of parallelization for this situation, although concurrency can be formally exposed.





• Aim: make OpenMP worksharing more flexible

Semantics:

- When a thread encounters a task construct, a task is generated from the code of the associated structured block.
- Data environment of the task is created (according to the data-sharing attributes, defaults, ...)
- The encountering thread may immediately execute the task, or defer its execution.

In the latter case, any thread in the team may be assigned the task.

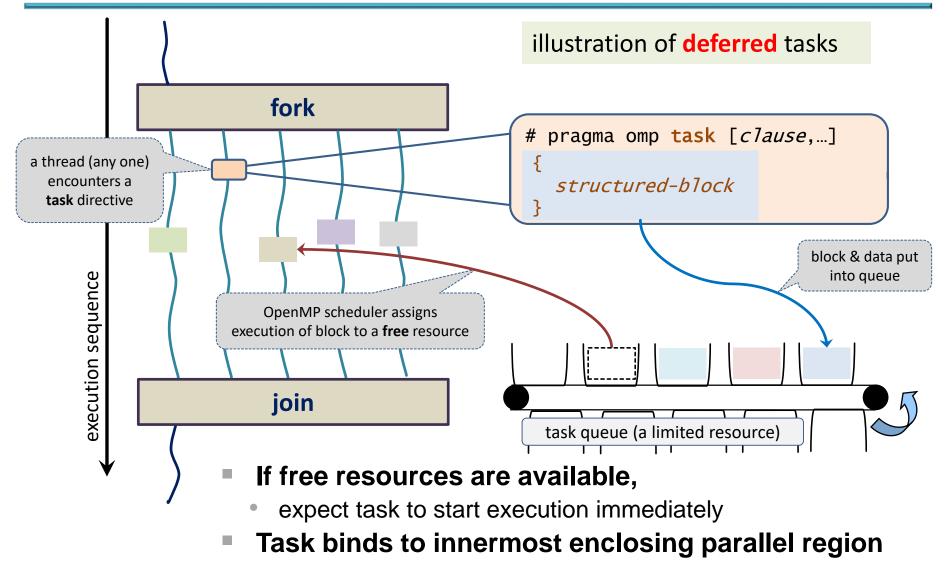
Introduced with OpenMP 3.0

additional features and improvements added in later versions of the standard



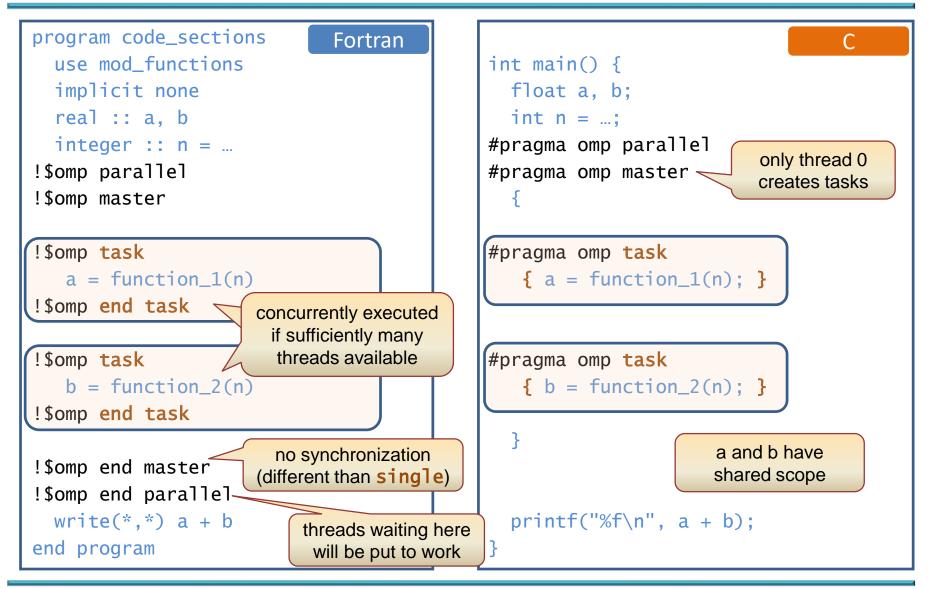
Concept of tasking





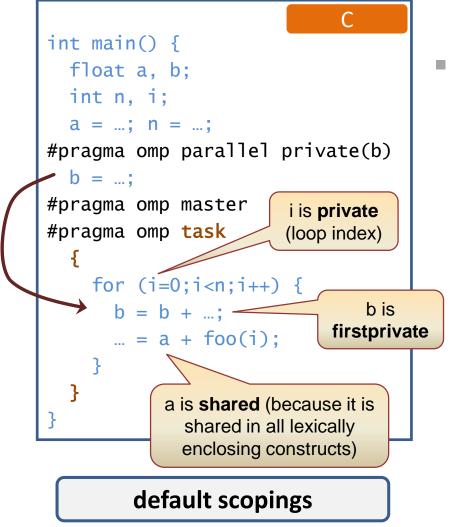










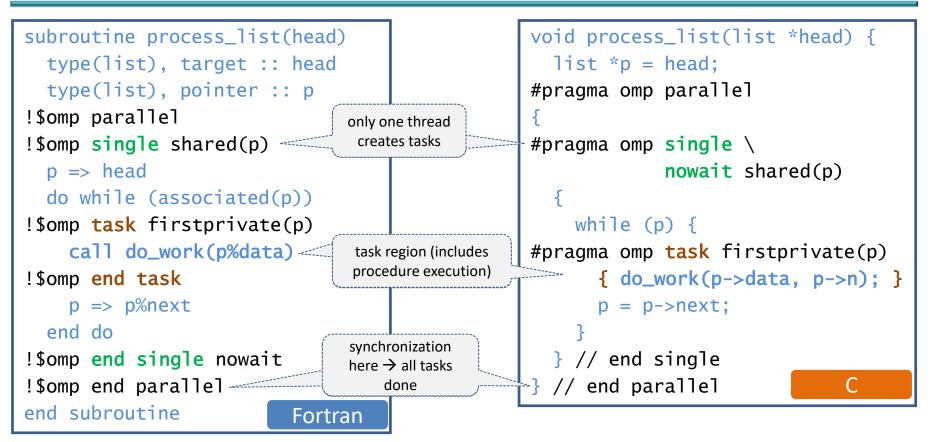


Recommendation:

- use a default(none) clause on all task directives
- explicitly specify the scoping for each data object







Need to have local pointer p firstprivate:

- avoid race condition on shared original (vs. subsequent update)
- assure that association status is copied to thread executing the task region



When "if" argument evaluates to "false",

- the parent task must suspend execution until the encountered task region has been completed (an "undeferred task"). However, it is not fully clear from the standard whether the child task must be executed by the same thread.
- but otherwise semantics are the same (with respect to data environment and synchronization) as for a "deferred" task

```
#pragma omp task firstprivate(p) if ( sizeof(p->data) > threshold )
        { do_work(p->data); }
```

User-directed optimization ("task pruning")

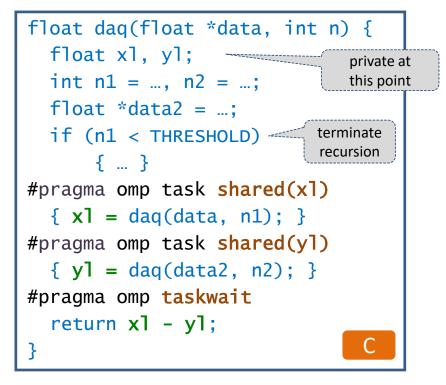
- avoid overhead for deferring small task
- avoid creating too many tasks (resource limits!)
- cache locality / memory affinity are likely to change

Fortran





Divide and conquer



 initial function invocation in a parallel region, usually from a single thread

Previous example:

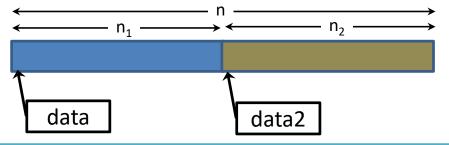
only sibling tasks are created

This example:

each task creates two child tasks
 → "deep hierarchy" of tasks

Scoping for x1, y1:

- start out as private variables
- only newly created tasks share scope with these variables
- shared scope is needed to communicate data outside the task regions



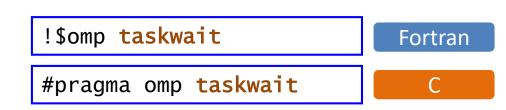




The taskwait directive

Syntax:

 suspends execution until immediate child tasks of current task complete (the directive does not apply for descendants of child tasks)



Needed in example from previous slide

- avoid race condition of assignments vs. evaluation
- avoid local variables vanishing into thin air while tasks are still executing





discussed

later

Possible issues with task scheduling:

- large number of tasks are created \rightarrow implementationdefined limit on unassigned tasks may be reached
- all currently active tasks reach a synchronization statement \rightarrow threat of deadlock?

Task switching

- permits a thread to suspend a task and start or resume another task at a task scheduling point
- for tied tasks, the same thread is obliged to resume execution of the suspended task later

Task scheduling points

immediately after generation of a task

at the end of a task region

in implicit or explicit barrier regions (wait until all tasks executed by the team are done)

in a taskwait region

in a taskyield region

at the end of a taskgroup region

e.g., a thread that creates lots of tasks may stop doing so and start working on one of them

tasks are tied by default ...



 a task assigned to a thread must be (eventually) completed by that thread → task is tied to the thread

Change this via the untied clause

execution of task block may change
 to another thread of the team at any task scheduling point

Deployment of untied tasks

• Starvation scenario:

Task switching has caused the task-generating thread to run a long calculation, with the result that all generated tasks were consumed and most threads idle.

If the task that generates the work is untied, a different thread can take over the task-generating workload.

Introduction to OpenMP



pragma omp task **untied** structured-block C







Thread-related semantics

used in the untied task region are likely to trip you up, for example ...

 relying on results delivered by omp_get_thread_num()

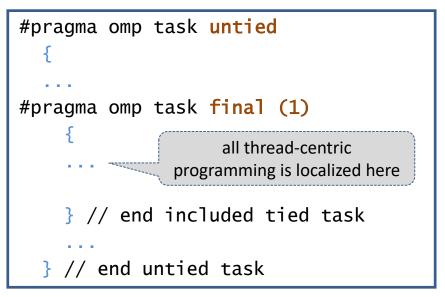
→ may become inconsistent after thread switch

 referencing and defining values stored in threadprivate global variables

→ may access a different copy after thread switch

Workaround

revert from untied to tied for the duration of problematic operations, if possible



• or use an "if (0)" clause (undeferred task might be executed by a different thread, though)





Use of threadprivate data by tied tasks

 value of threadprivate variables cannot be assumed to be unchanged across a task scheduling point. Might have been modified by another task executed by the same thread.

Tasks and locks:

Note: locks are owned by tasks, not threads

 if a lock is held across a task scheduling point, interleaved code trying to acquire it (maybe using the same thread) may cause deadlock

Comment: implementation-defined task scheduling points in **untied** tasks have been removed from the standard

Tasks and critical regions:

 similar issue if suspension of a task happens inside a critical region and the same thread tries to access the same critical region in another scheduled task

Tools?

• correctness tools will currently only find some of the issues that can arise

Programmer-defined task scheduling points





 permits (but does not force) task suspension for the current task at the point where the directive is placed

Example

 avoid deadlock in a mutual exclusion region (taken from the OpenMP examples)

```
subroutine foo ( lock, n )
  use omp_lib
  integer(kind=omp_lock_kind) :: lock
  integer :: n
  integer :: i
  do i = 1, n
!$omp task
    call something_useful()
    do while &
       ( .not. omp_test_lock(lock) )
!$omp taskyield
    end do
    call something_critical()
    call omp_unset_lock(lock)
!$omp end task
  end do
                              Fortran
end subroutine
```

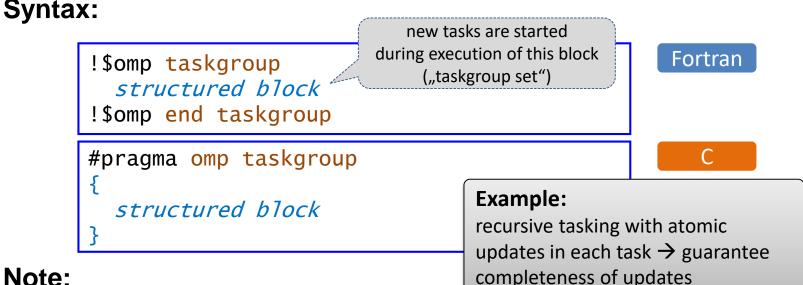




 \leftrightarrow taskwait

Purpose:

- synchronize all tasks created inside a structured block
- includes all descendants, not only immediate child tasks
- synchronization (i.e. waiting for task completion)
 happens at the end of the taskgroup region (task scheduling point)



Note:

 tasks that were created before the taskgroup region started execution are not synchronized

 \leftrightarrow taskwait, barrier





Final tasks

- use a final clause with a condition on a task directive
- if the condition evaluates to "true", the resulting task is always undeferred, and is immediately executed by the parent task's thread
- reduces the overhead of placing tasks in the "task pool"
- all tasks created inside task region are also final (different from an **if** clause)
- inside a task block, omp_in_final() can be used to check whether the task is final

Merged tasks

- using a mergeable clause may create a merged task if it is undeferred or final
- a merged task has the same data environment as its creating task region

Final and/or mergeable

- can be used for optimization purposes
- e.g. to optimize wind-down phase of a recursive algorithm

current implementations seem not to actively support merging.







Syntax

!\$omp task **priority(**priority_value)

#pragma omp task priority(priority_value)



Semantics

- provides a hint to the run time on prioritizing (ordering) task execution
- the priority value must be a non-negative integer; higher values correspond to higher priorities; maximum value is omp_get_max_task_priority()
- do not rely on a particular ordering of tasks imposed by specifying a priority

#pragma omp task priority(9999)
 participants.get_coffee(100);



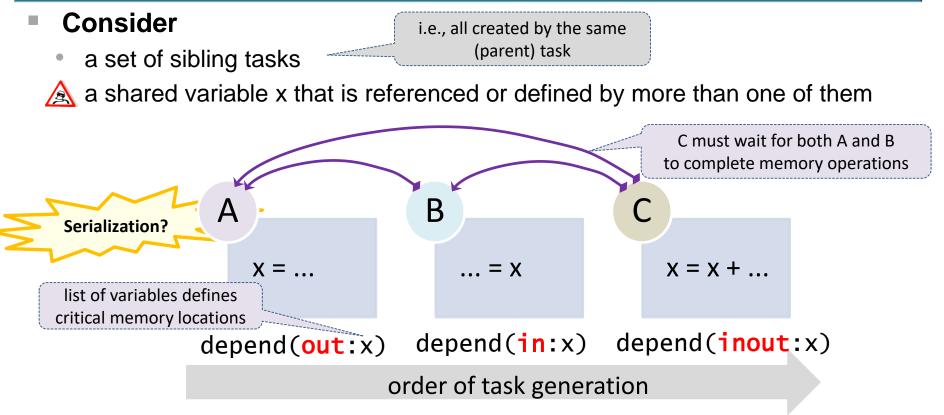


Example program Observed output with 3 threads can be any of ... s1 = ''; s2 = 'and'; s3 = 'chaos' and order chaos order chaos and chaos order and !\$omp parallel order and chaos !\$omp master chaos and order !\$omp task and chaos order s1 = 'order' write(*, fmt='(a)', advance='NO') trim(s1) // ' ' !\$omp end task !\$omp task write(*, fmt='(a)', advance='NO') trim(s2) // ' ' !\$omp end task !\$omp task write(*, fmt='(a)', advance='NO') trim(s3) // ' ' !\$omp end task !\$omp end master !\$omp end parallel write(*, fmt='(a)', advance='NO') new_line('a')



Introducing data-driven dependencies: the "depend" clause





- in dependence: synchronizes memory operations against previously started tasks with an inout or out dependence on same memory location
- **out or inout dependence:** synchronizes memory operations against **any** defined dependence on **same** memory location for previously started task





Observed output with 3 threads can only be

order and chaos

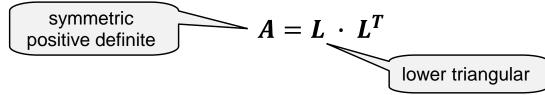
Via addition of depend clauses

```
s1 = ''; s2 = 'and'; s3 = 'chaos'
                                             The type of memory operation that is actually
                                             performed is irrelevant for the ordering
!$omp parallel
                                             properties (although it usually determines
!$omp master
                                             what type of dependency must be declared to
!$omp task depend(out:s1)
                                             avoid race conditions)
  s1 = 'order'
 write(*, fmt='(a)', advance='NO') trim(s1) // ' '
!$omp end task
!$omp task depend(in:s1) depend(out:s2)
 write(*, fmt='(a)', advance='NO') trim(s2) // ' '
!$omp end task
!$omp task depend(in:s2)
 write(*, fmt='(a)', advance='NO') trim(s3) // ' '
!$omp end task
!$omp end master
!$omp end parallel
  write(*, fmt='(a)', advance='NO') new_line('a')
```

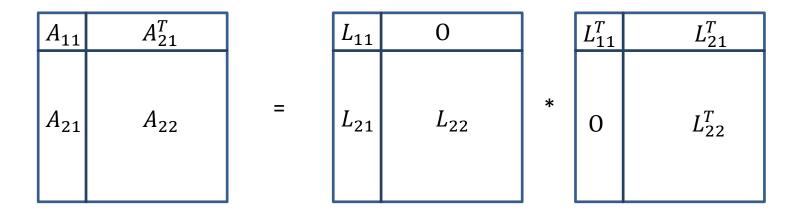




Drawing the square root of a matrix



Recursive blocked algorithm



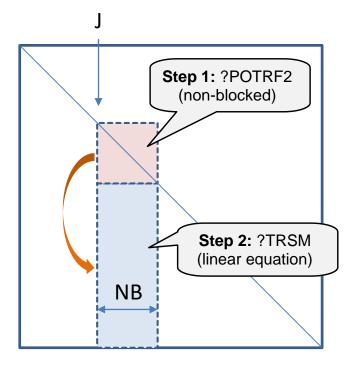
LAPACK algorithm ?POTRF





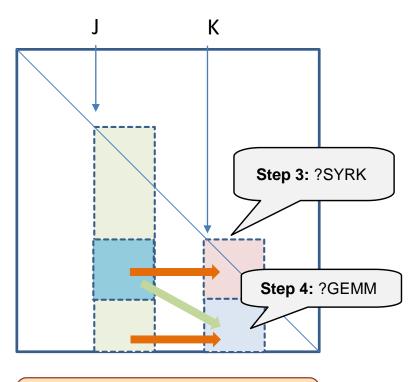
Phase 1

- one thread only
- "hot" block column is J



Phase 2

parallel updates of columns
 K = J+NB, J+2*NB, ...



load imbalance → use suitable schedule





```
!$OMP PARALLEL PRIVATE(JB, KB)
 DO J = 1, N, NB
    JB = MIN(NB, N-J+1)
!SOMP SINGLE
Update the current diagonal block
 A(J,J), JB by JB and test for
!
  non-positive-definiteness
CALL POTRF2( ... )
    IF ( J+JB.LE.N ) THEN
! using the above, solve for
! A(J+JB,J), N-J-JB+1 by JB
     CALL DTRSM( ... )
    END IF
!SOMP END SINGLE
    . . .
```

```
!$OMP DO SCHEDULE(...)
   DO K = J + NB, N, NB
     KB = MIN(NB, N-K+1)
! Update diagonal block A(K,K)
! from A(J,K)
     CALL DSYRK( ... )
     IF ( K+KB.LE.N ) THEN
! Update subdiagonal block A(K+KB,K)
! from A(K+KB,J) and A(K,J)
       CALL DGEMM( ... )
     END IF
   END DO
!$OMP END DO
END DO
!SOMP END PARALLEL
```

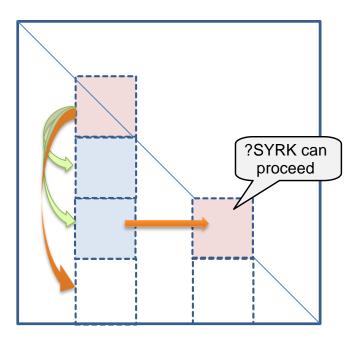
Reminiscence:

- Parallelization of Linear Algebra Algorithms on the KSR1, R. Bader (1994)
- same basic structure of algorithm, but OpenMP is more elegant



Phase 1:

 multithread the TRSM update by subdividing the block column



Phase 2:

- multithread the GEMM update by subdividing the block column
- pipelined startup of SYRK/GEMM updates possible as phase 1 blocks complete

Tasking makes this easy to do

Requirement:

need to specify the data dependencies

→ Fortran array sections in depend clauses

Note:

 nested parallelism has more overhead and is more difficult to manage





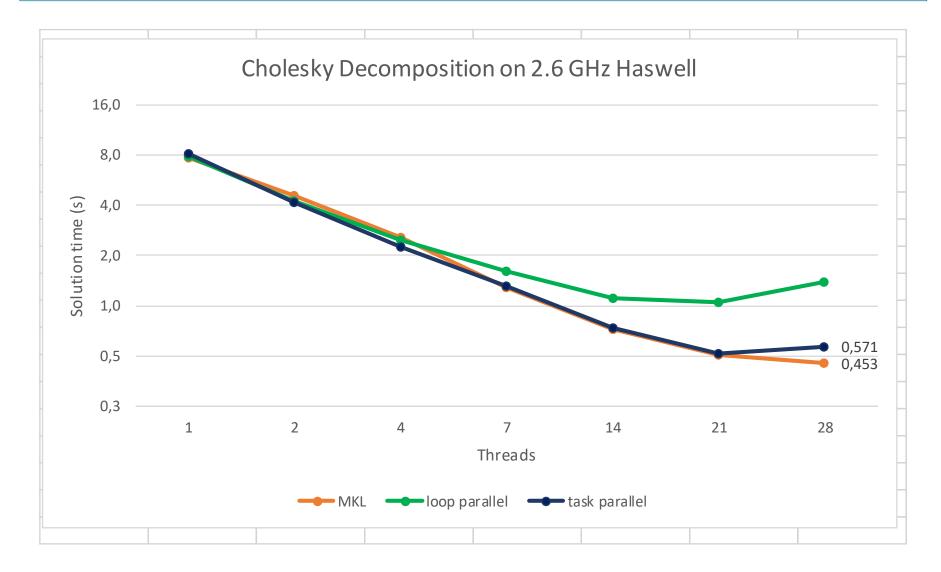
```
!$OMP PARALLEL PRIVATE(JB, JJB, KB)
 DO J = 1, N, NB
    JB = MIN(NB, N-J+1)
!SOMP SINGLE
!SOMP TASK &
!$OMP& DEPEND(inout: &
!$OMP& A(J:J+JB-1,J:J+JB-1))
   CALL POTRF2( ... )
!SOMP END TASK
   DO JJ = J+JB, N, NB
       JJB = MIN(NB, N-JJ+1)
!SOMP TASK &
!$OMP& DEPEND(in: &
!$OMP& A(J:J+JB-1,J:J+JB-1)) &
!$OMP& DEPEND(inout: &
!$OMP& A(JJ:JJ+JJB-1,J:J+JB-1))
       CALL DTRSM( ... )
!SOMP END TASK
                        explicit
    END DO
                     synchronization
                      point removed
```

```
DO K = J + NB, N, NB
    KB = MIN(NB, N-K+1)
!$OMP TASK DEPEND(in: &
!$OMP& A(K:K+KB-1,J:J+JB-1))
!$OMP& DEPEND(inout: &
!$OMP& A(K:K+KB-1,K:K+KB-1))
    CALL DSYRK( ... )
!SOMP END TASK
    DO JJ = K+KB, N, NB
         JJB = MIN(NB, N-JJ+1)
!$OMP TASK DEPEND(in: &
!$OMP& A(JJ:JJ+JJB-1,J:J+JB-1),&
!$OMP& A(K:K+KB-1,J:J+JB-1))
!$OMP& DEPEND(inout: &
!$OMP& A(JJ:JJ+JJB-1,K:K+KB-1))
      CALL DGEMM( ... )
!SOMP END TASK
    END DO
  END DO
!$OMP END SINGLE
END DO
!SOMP END PARALLEL
```



problem size: n = 10,000, block size: nb = 256

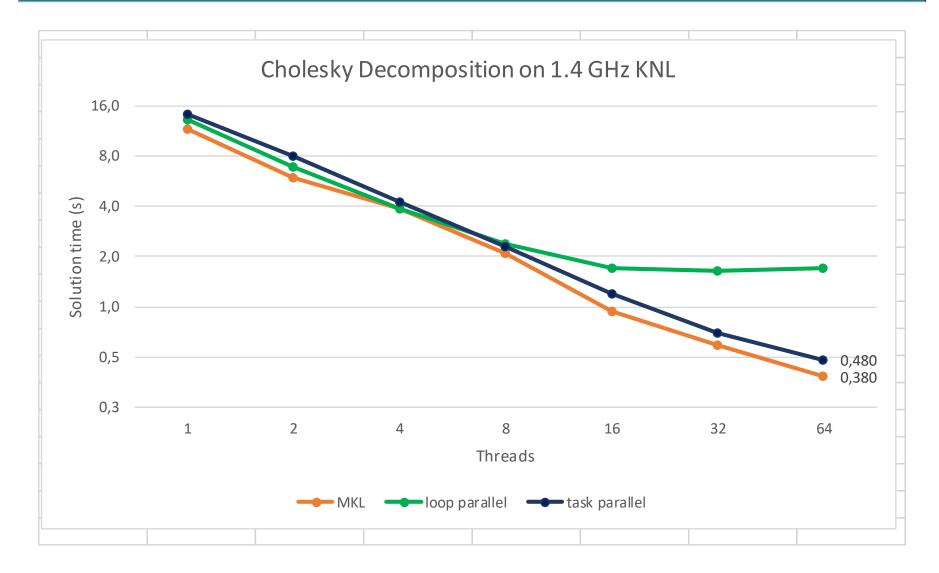






problem size: n = 10,000, block size: nb = 256









Comparing the N = 6000 solution time

	KSR1 (24 cells)	Haswell (28 cores)	KNL (64 cores)
year of release	1992	2014	2015
solution time (s)	270	0.13	0.16
GFlop/s	0.267	566	440
	memory limit of machine		strong scaling limit

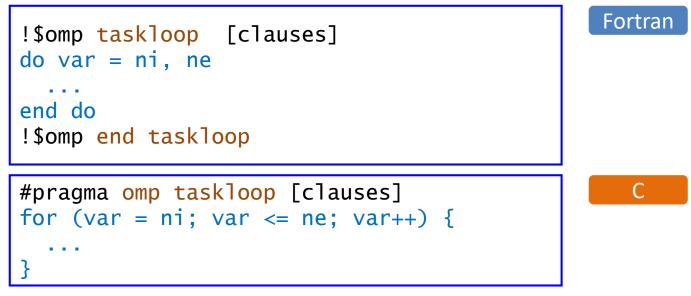






Tasking and worksharing loops:

- coexistence is difficult, because tasks are often issued in a context that does not permit application of "omp do/for"
- creating a task for each loop iteration may be too fine-grained
- New construct: taskloop



creates task regions for iterations of associated loop(s)





- Scoping:
 - private, firstprivate, shared, default
- Inherited from work sharing:
 - collapse, lastprivate
- Inherited from tasking:
 - if, final, mergeable, priority, untied

New clauses:

- grainsize(size)
- num_tasks(num)

nogroup

Now: 6th exercise session

Current compiler support is very limited

reduction support targeted for next standard

constrains number of iterations assigned to each task (upper limit < 2*grainsize)

maximum number of tasks created

by default, a taskloop construct **implies** a taskgroup region. This is similar to the sync at the end of a worksharing construct. The nogroup clause **removes** this additional synchronization.





Performance:

Architectural aspects





- What can be expected from the processor architecture?
 - want at least an estimate for performance limits → avoid "stumbling in the dark"
 - much more detailed node performance engineering and modeling: course by G. Hager and G. Wellein – see

http://moodle.rrze.uni-erlangen.de/moodle/course/view.php?id=300&username=guest&password=guest&lang=en

and references cited within

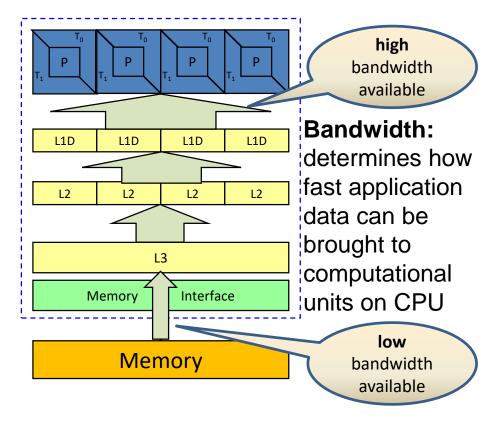
- How to exploit the architecture as best as possible
 - use optimal data access patterns
 - minimize synchronization overhead
 - Account for interactions of OpenMP features with "serial" optimization techniques (might be compiler optimization or lack thereof!)





Performance Characteristics

 determined by memory hierarchy



- Impact on Application performance: depends on where data are located
 - temporal locality: reuse of data stored in cache allows higher performance
 - no temporal locality: reloading data from memory (or high level cache) reduces performance

For multi-core CPUs,

 available bandwidth may need to be shared between multiple cores

 \rightarrow shared caches and memory





- A small but fast memory area
 - used for storing a (small) memory working set for efficient access

Reasons:

 physical and economic limitations

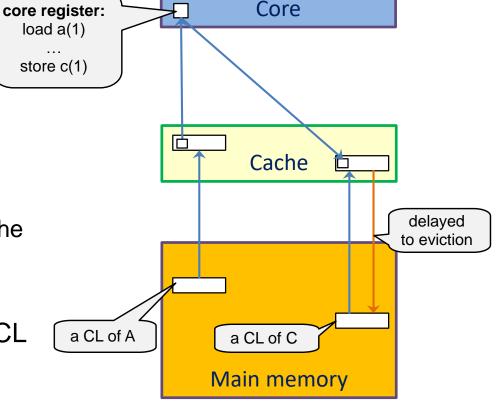
Loads (stores) to (from) core registers

 may trigger cache miss → transfer of memory block ("cache line", CL) from memory

Cache fills up …

usually least recently used CL is evicted









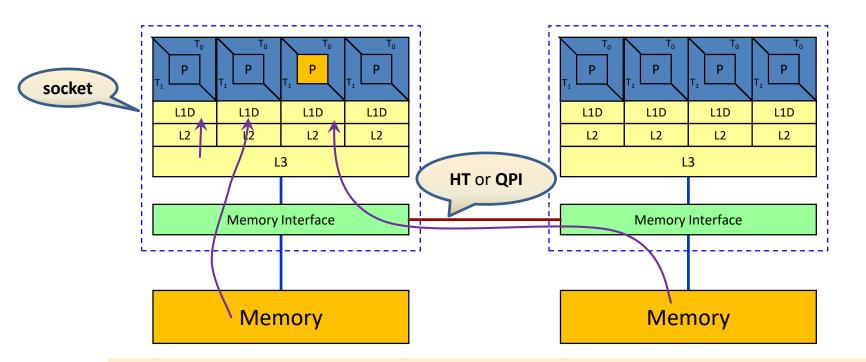
Control of Affinity NUMA effects False Sharing





- multi-core multi-threaded processors with a deep cache hierarchy
- typically, two **sockets** per node

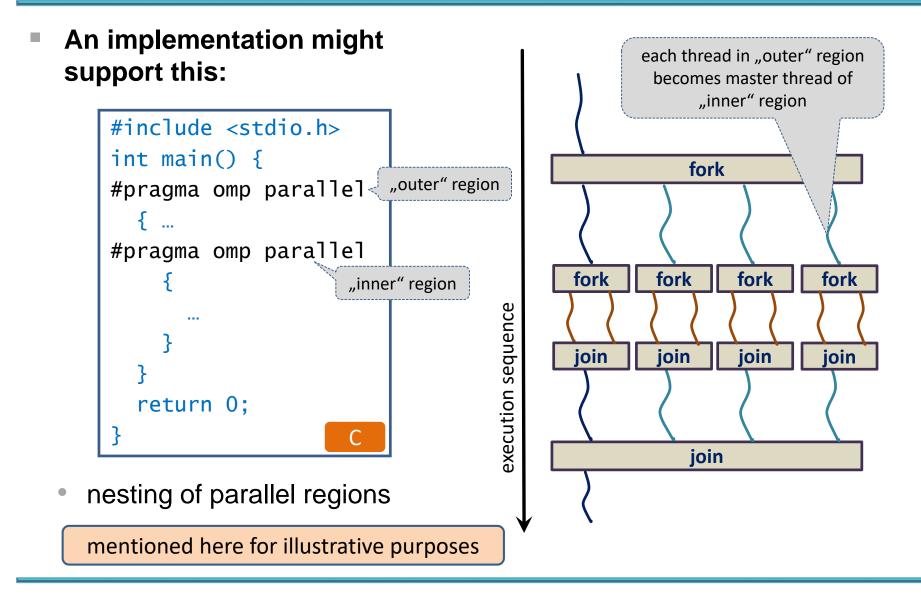
Illustration shows 4 cores per socket. Current sockets have 8 – 14 cores



ccNUMA architecture: "cache-coherent non-uniform memory access"

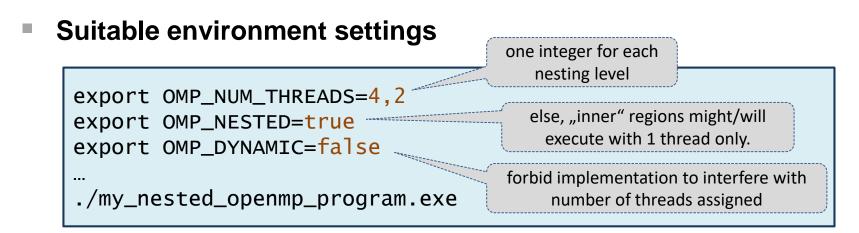












Operating system:

- responsible for assigning hardware resources to threads
- in general not trivial note that (active) thread count can change during execution
- Possible issues (performance impact):
 - threads might move around between cores
 - multiple threads might share a core (or other resources)

 \rightarrow a mechanism for controlling thread affinity / binding is desirable





Two aspects:

- 1. What entity should a thread be bound to? \rightarrow concept of place
- 2. How should the binding be performed (if at all ...)?
- **Optimal binding strategy** depends on machine and application
- Putting threads far apart ("spread", "scatter") might
 - improve aggregate memory bandwidth
 - improve combined cache size
 - decrease performance of synchronization constructs
- Putting threads close together (i.e. on two adjacent cores) might
 - improve performance of synchronization constructs
 - decrease available memory bandwidth and cache size per thread

→ available since **OpenMP 4.0**

before that: implementation-specific mechanisms



OpenMP place: a container unit for pinning of threads



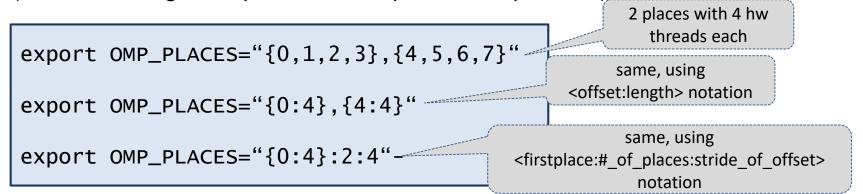
Places are defined via either

 an abstract name (threads, cores, or sockets), optionally followed by a bracketed positive integer (number of places):

export OMP_PLACES="cores(8)"

8 places with 1 physical core each

 or an explicit list of places, specified as list of integer intervals (in the following example, all three specs are equivalent)



meaning of the index is **implementation defined**, but you can expect the smallest unit of execution (a hardware thread on x86) to be used.





- Determine whether threads should be pinned
 - environment variable OMP_PROC_BIND
 - with values true or false, or
 - a comma-separated list of entries:

master	bind created threads to same place as master thread						
close	bind created threads to a place close to the one assigned to the master						
spread	use a sparse distribution pattern to bind created threads to places						

Example:

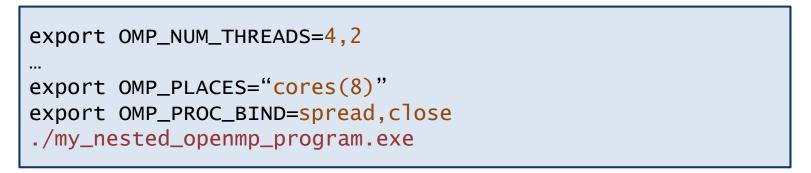
export OMP_PROC_BIND=spread,close

• binding is determined for at most two levels of parallel nesting

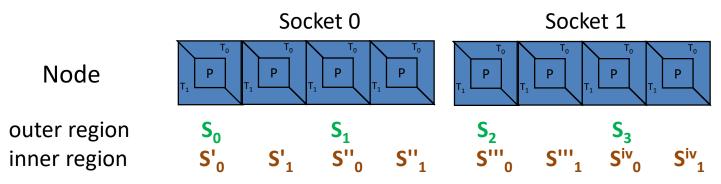




Nested parallelism example from earlier



Threads are named S_i, and S'_i, S"_i, ..., for outer and inner region, respectively:



Overcommitment causes places to be reused (i.e. multiple threads per place)





Fortran

C

The function

integer(...) function omp_get_proc_bind()

omp_proc_bind_t omp_get_proc_bind(void)

returns one of the following constants:

omp_proc_bind_false	0
<pre>omp_proc_bind_true</pre>	1
omp_proc_bind_master	2
<pre>omp_proc_bind_close</pre>	3
omp_proc_bind_spread	4

The value may depend on the nesting level from which the function is called





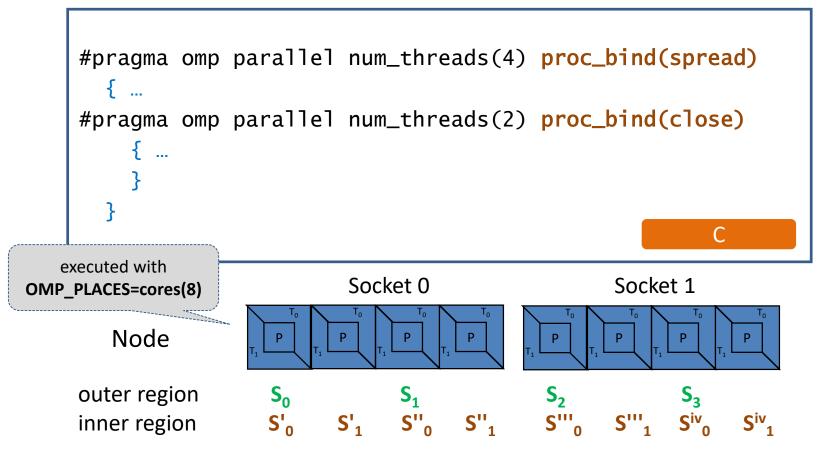
A number of functions exist to handle various inquiries:

Name	Result type	Purpose
<pre>omp_get_num_places()</pre>	int	number of places available
omp_get_place_num_procs (int place_num)	int	number of processors available in place_num (0 number of places - 1)
<pre>omp_get_place_proc_ids (int place_num, int *ids)</pre>	void	ids contains numerical identifiers of processors in place place_num
<pre>omp_get_place_num()</pre>	int	place number of place to which calling thread is bound
<pre>omp_get_partition_num_places()</pre>	int	number of places in place partition of innermost implicit task
<pre>omp_get_partition_place_nums</pre>	void	list of place numbers for innermost implicit task





- A proc_bind clause can be specified
- Example:







Topology =

- Where in the machine does core #n reside?
- awkward numbering anyway?
- which cores share which cache levels
- which hardware threads ("logical cores") share a physical core?

Use LIKWID tool to identify

- developed by J. Treibig
- see

http://code.google.com/p/likwid for source code and documentation

- Available commands
 - likwid-topology: Print thread and cache topology
 - likwid-pin: Pin threaded application without touching code

- likwid-perfctr: Measure performance counters
- likwid-mpirun: mpirun wrapper script for easy LIKWID integration
- likwid-bench: Low-level bandwidth benchmark generator tool
- ... some more





Output of likwid-topology –g (ASCII art section):

Socket 0: +	+	hyperthreaded
0 16 1 17 2 18 3 ++ ++ ++ + ++ ++ ++ + 32kB 32kB 32kB 32kB 32 ++ ++ ++ ++ ++ ++ ++ ++ 256kB 256kB 256kB 256kB 256	19 4 20 5 21 6 22 7 23 1 + ++ ++ ++ + + ++ ++ ++ + 2kB 32kB 32kB 32kB 32kB 32kB 32kB + 1 + ++ ++ ++ + 6kB 256kB 256kB 256kB 256kB 256kB 1	L1D L2
 +	20MB +	shared L3
	+ ++ ++ ++ ++ + 11 27 12 28 13 29 14 30 15 + ++ ++ ++ ++	each socket forms
32kB 32kB 32kB ++ ++ ++ ++ ++		B +
256kB 256kB 256kB ++ ++ ++ ++	+ ++ ++ ++ ++ ++ 256kB 256kB 256kB 256kB 256 + ++ ++ ++ ++	kB
	20МВ	+ +





Output of likwid-topology –g (ASCII art section):

Soc	ket 0:															
+ 	++ 0	+- 	 1	+ +	2	·+ · 	++ 3	+ • 	+ 4	+- 	5	+ + ا	+ 6	+ I	 7	+ single threaded cores
+ +	+ + 64kB	+-	 64kB	+ + + + 1 1	 64kB	·+ · ·+ ·	++ ++ 64kB	• + • + ।	+ + 64kB	+ · + ·		+ 4 + 4	+ + 64kB	+	 4kB	+
+ +	+	+- +-		+ + + +	+	-+ -	++	• +	•	+-			+	+		+ 1
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 + +				5MB	3		 +	 +			5	5ME	3			shared L3
Soc +	ket 1:								·							+
+ +	8 +	+-	9 	+ + + +	10	·+ · -+ ·	11 ++	 +	12 +	 +-	13	 	14 +	+	15 	 each socket forms two NUMA domains
+ +	+ 64kB +	+- +-				•	++ 64kB ++	I	64kB	I	64kB		•	6	4kB	
+ +	+ 512kB +	1			512kB	I	512kB	I	+ 512kB +	I	512kB		512kB	51	2kB	
+ 	++ 5MB						+ · 	++ 5MB ++						+ +		
1 1							•	•								• •





Pins processes/threads to specific cores without touching code

- Directly supports pthreads, gcc OpenMP, Intel OpenMP
- Based on combination of wrapper tool together with overloaded pthread library → binary must be dynamically linked!
- Can also be used as a superior replacement for Linux command taskset
- Supports logical core numbering within a node and within an existing CPU set
 - Useful for running inside CPU sets defined by someone else, e.g., the MPI start mechanism or a batch system

Usage examples:

Physical numbering (as given by likwid-topology):

likwid-pin -c 0,2,4-6 ./myApp parameters

• Logical numbering by topological entities:

likwid-pin -c S0:0-3 ./myApp parameters



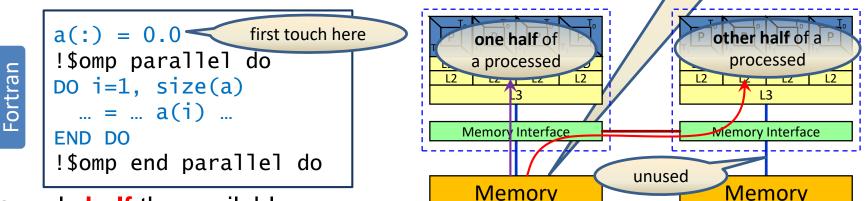


all of a(:) physically located here

- Allocation of memory (with C malloc() / Fortran ALLOCATE)
 - only provides a virtual memory address
- Physical memory
 - is assigned when a memory location is initialized ("first touch")
 - units of pages (note overhead due to page faults!)

Consequence for OpenMP

possible memory accesses across socket boundaries



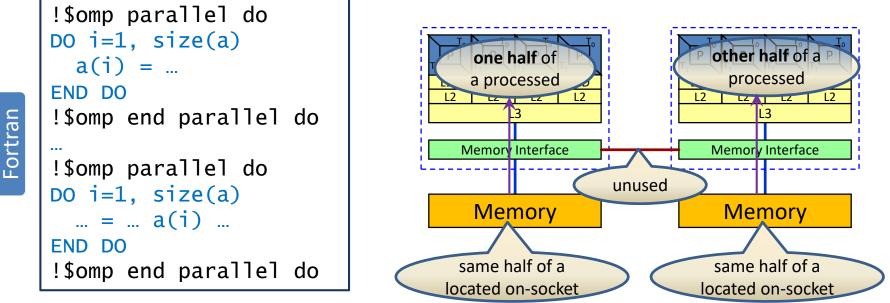
only half the available

memory BW might be exploited on a 2-socket system





- Desirable and scalable memory access pattern:
 - requires initialization with an OpenMP parallelized loop
- Distributed first touch
 - ideally, uses same loop schedule as later processing



• now, the full available

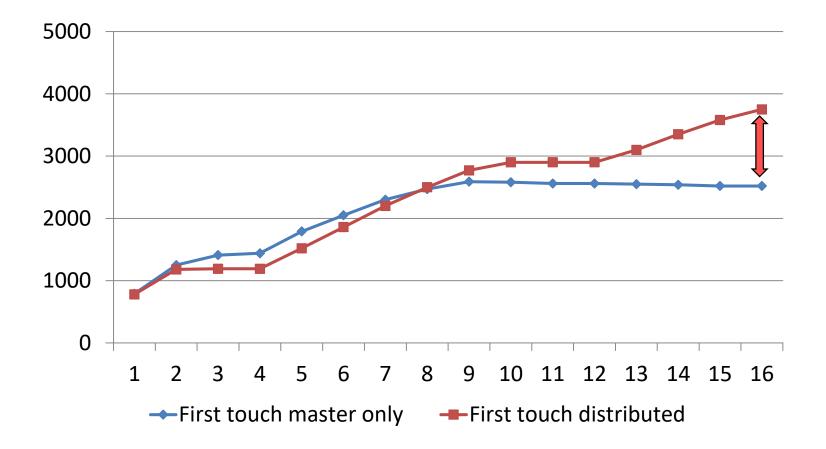
memory BW can be exploited on a multi-socket system





Measured on two AMD Magny Cours sockets

thread pinning uses "close" strategy





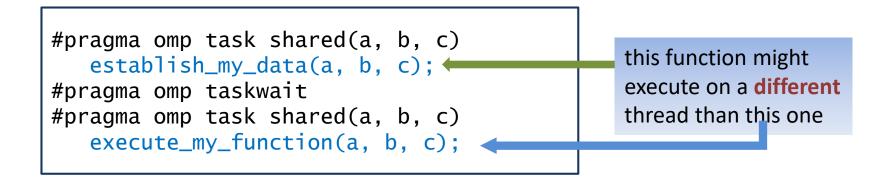


- Remember:
 - tasking decouples data items and associated functions from the threading model

```
#pragma omp task
    execute_my_function(a, b, c);
```

Consequence:

 repeated execution of tasking on data items might use different threads → memory affinity will get lost!

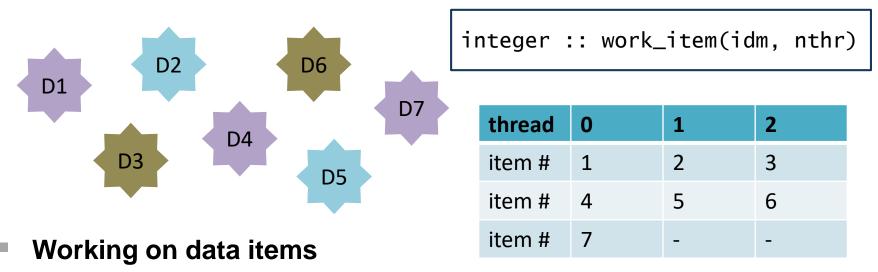






At initialization

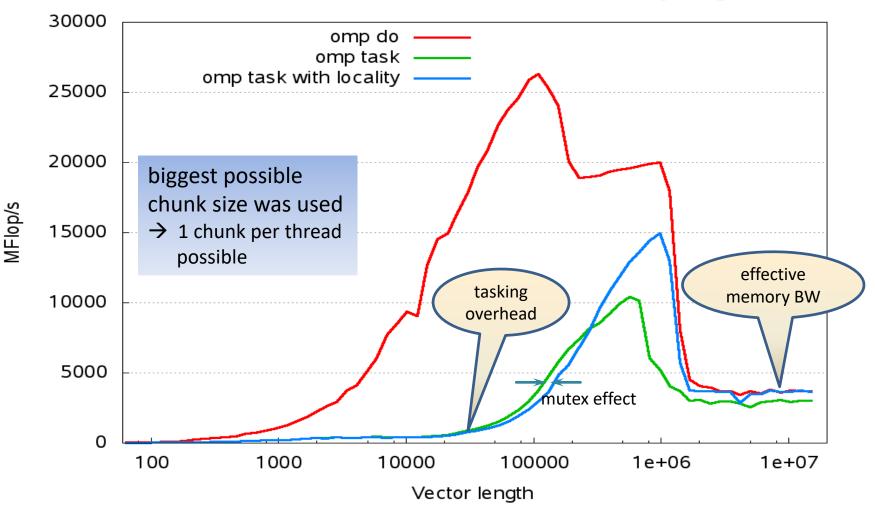
store which thread performed it – threads are color coded below



- first work on items that are local to the executing thread
- next work on items that are located elsewhere (nearby first)
 > task stealing due to unpredictable thread assignment
- additional bookkeeping (mutual exclusion) is needed to assure complete and unique execution



work shared vector triad with 16 threads on Sandy Bridge





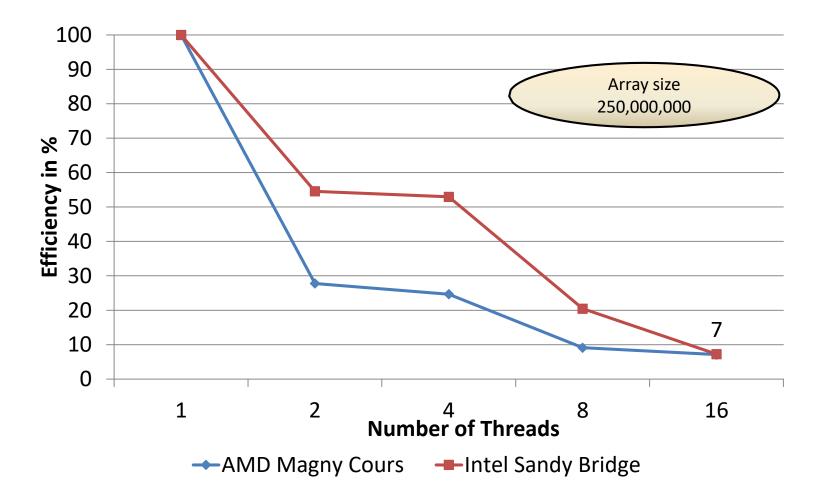


Example program: count even and odd array values

```
integer is(2), ict(2,ntdm), ia(n)
                                      initialization omitted
  ....
!$omp parallel private(myid) shared(ict, ia)
  myid = omp_get_thread_num()+1
!$omp do private(index)
  do i=1,n
    index = mod(ia(i), 2)+1
    ict(index,myid) = ict(index,myid) + 1
  end do
                                    formally correct,
!$omp end do
                                    no race condition
!$omp critical
  is = is + ict(1:2,myid)
!$omp end critical
!$omp end parallel
                                                  Fortran
```



Baseline 1 thread execution time: AMD 0.75 s, Intel SandyBridge 0.37 s

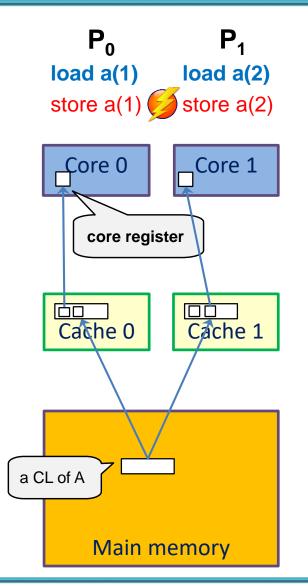


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Updating neighbouring data from different cores





Store operation

- write back always done on complete cache lines
- "merging of partial cache lines" is not possible

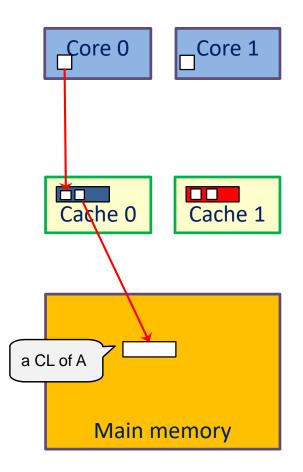
Cache coherence protocol

- keeps track of cache line status
- assures data consistency by enforcing hardware synchronization between writes





Diagram shows state after step 3



- Hardware execution sequence for write on Core 0:
 - 1. Request exclusive access to CL (Core 0 issues it first)
 - 2. Invalidate CL in Cache 1
 - 3. Modify CL in Cache 0 (exclusively owned)
 - 4. mark CL shared
- Hardware execution sequence on Core 1:
 - 5. Request CL from memory for reading (granted after CL is marked shared)
 - 6. Request exclusive access to CL
 - 7. Invalidate CL in Cache 0
 - 8. Modify CL in Cache 1 (exclusively owned)
 - 9. mark CL shared





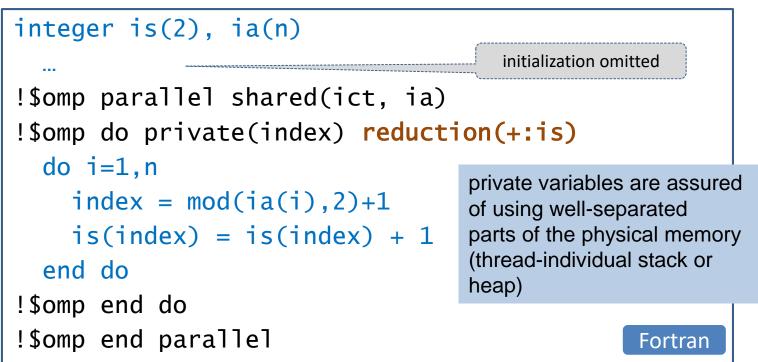
Repeated access to data in same cache line:

- causes thrashing of cache lines
- for each access, more than twice the memory latency may be accumulated, resulting in significant performance reduction
- This effect is called "false sharing"





Privatization – here through use of a reduction variable



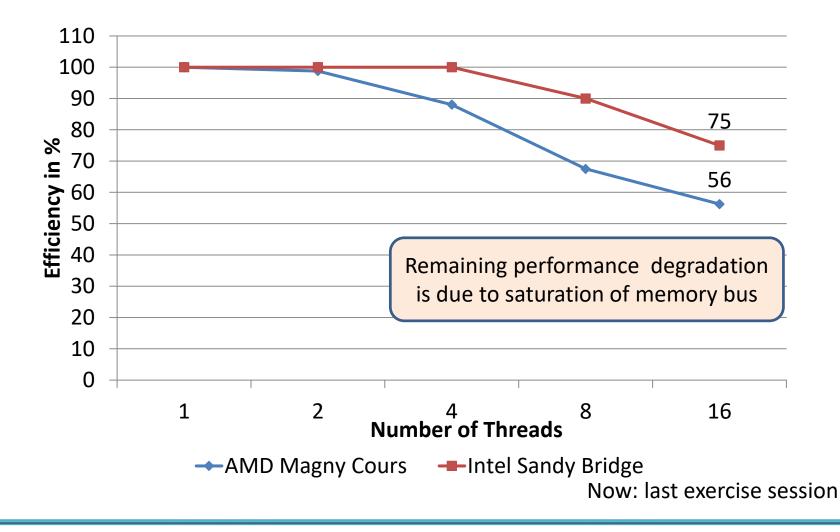
Alternative for retaining shared variables: Add padding

tradeoff: may lose spatial locality





Baseline 1 thread execution time: AMD 0.81 s, Intel SandyBridge 0.36 s



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Outlook: Towards quantifying performance





Characteristics

- known operation count, load/store count
- some variants of interest:

Kernel	Name	Flops	Loads	Stores
$s = s + a_i * b_i$	Scalar Product	2	2	0
$n^2 = n^2 + a_i * a_i$	Norm	2	1	0
$a_i = b_i * s + c_i$	Linked Triad (Stream)	2	2	1
$a_i = b_i * c_i + d_i$	Vector Triad	2	3	1

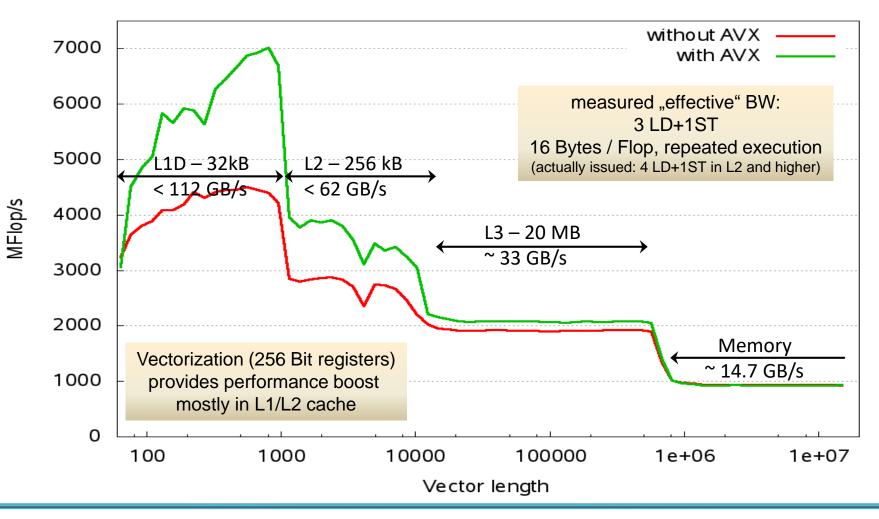
run repeated iterations for varying vector lengths (working set sizes)





Synthetic benchmark: bandwidths of "raw" architecture

for a single core Sandy Bridge 2.7 GHz / ifort 13.1

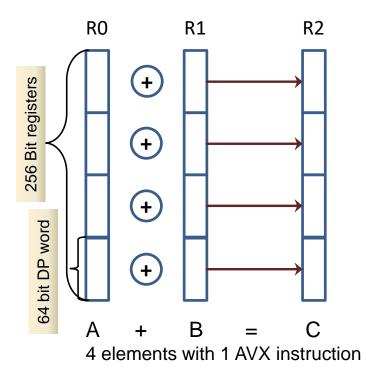






Sandy Bridge vector unit:

- 256 Bit SIMD (single instruction multiple data)
- Example: addition of 8 Byte words



- Instruction capability
 - 1 vector add and 1 vector mult per cycle → theoretical Peak 8 Flops/cycle

LD/ST issue capability

- 4 Words LD/cycle
- 4 Words ST/(2 cycles)

Only L1 might maintain needed bandwidth

- Vector triad:
 - required loads limit performance
 to 8 Flops / 3 cycles

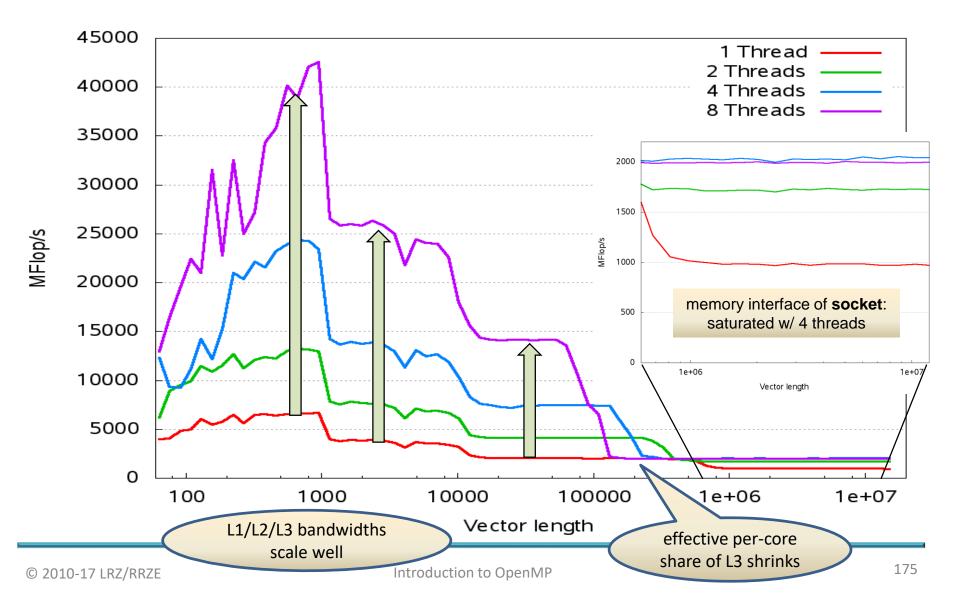
i.e. 7.2 GFlop/s at 2.7 GHz

 Consult processor-specific architecture manual



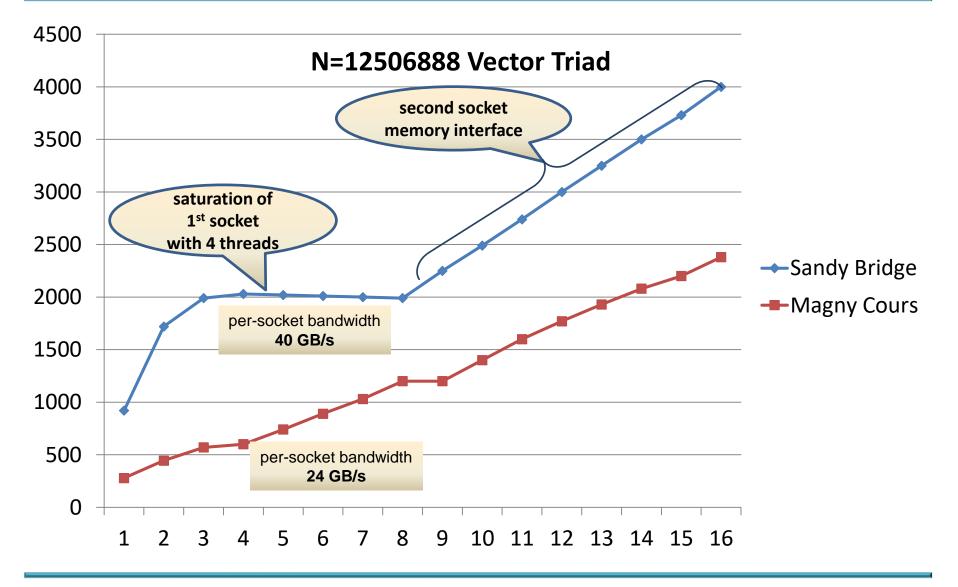


Throughput mode: run with independent threads up to number of cores on a socket



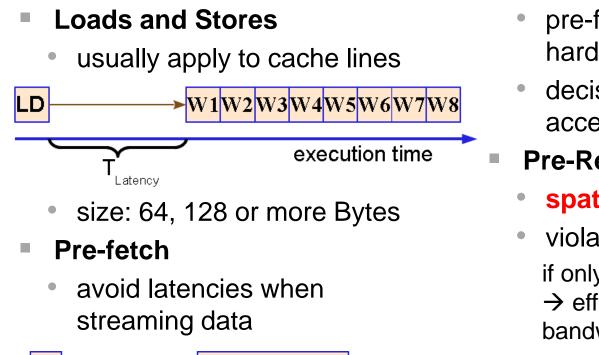










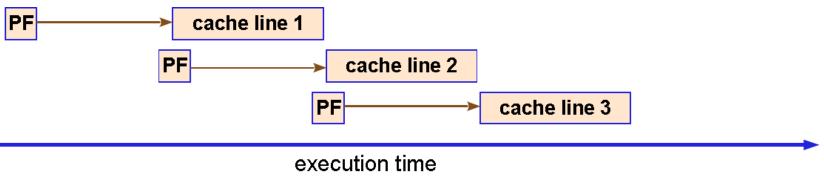


- pre-fetches usually done in hardware
- decision according to memory access pattern

Pre-Requisite:

- spatial locality
- violation of spatial locality:

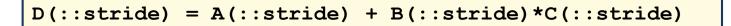
if only part of a cache line is used → effective reduction in bandwidth

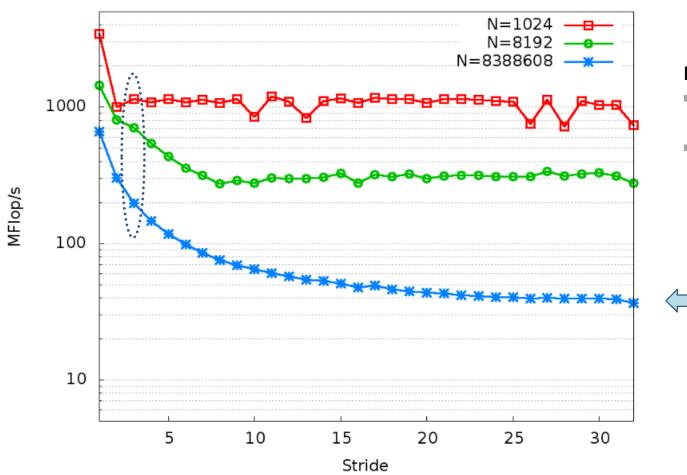




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Performance of strided triad on Sandy Bridge - loss of spatial locality









stride known at compile time

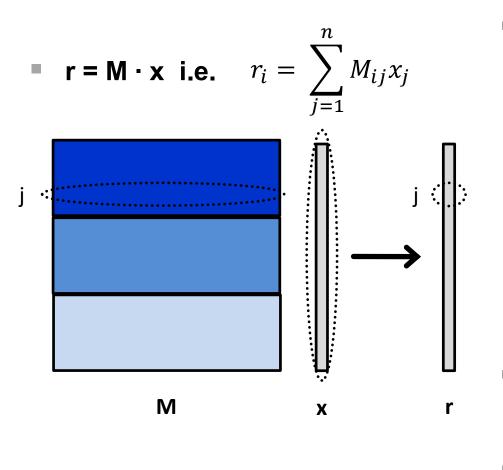
Example: stride 3

 serial compiler optimizations may compensate performance losses in real-life code

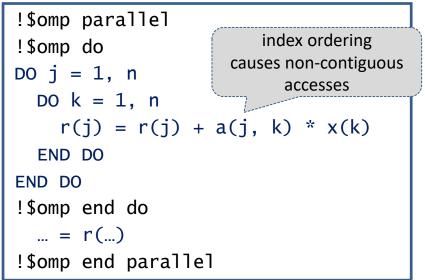
> ca. 40 MFlop/s (remains constant for strides > ~25)

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First parallelization attempt:



Parallel patterns used:

- data decomposition (load balanced)
- loop parallelism (no dependencies)

Directive placement:

 coarse grained parallelism to avoid synchronization overhead

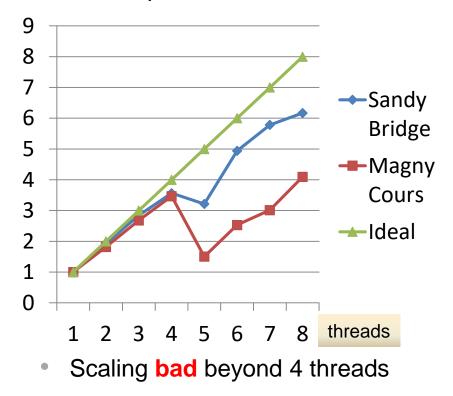


Measured performance (size 8000)



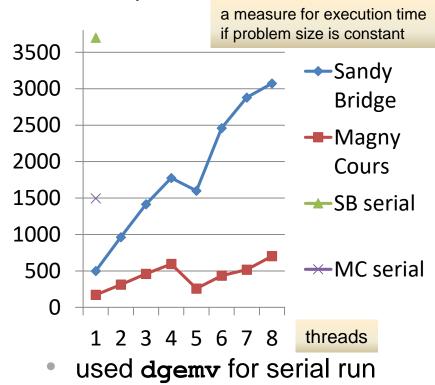


as a function of number of threads on 8-core processors



Absolute performance:

• MFlop/s = $2 \cdot n^2$ / time

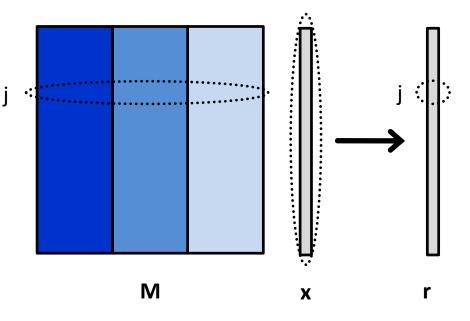


Speed-Up useless if baseline performance is bad



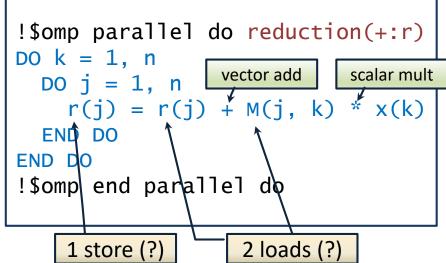


- Switch loop order
 - map column blocks to threads:



 color code indicates thread assignment Variant 2 of code:

- contiguous access to M
- array reduction on result vector

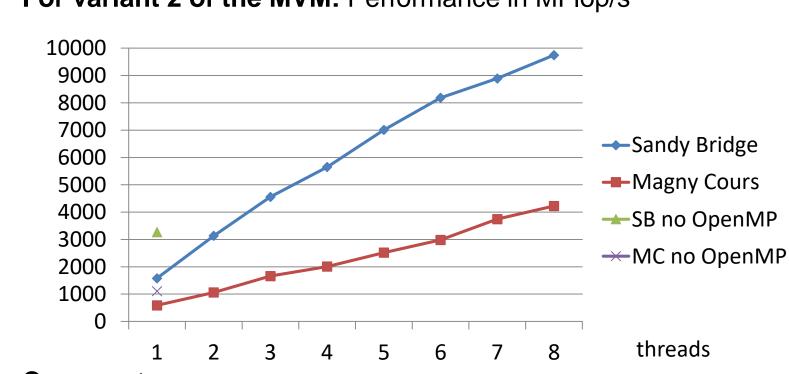


- Performance estimate for single thread:
 - double that of triad \rightarrow 1.86 GFlop/s

Cannot be the whole truth – remember serial performance: 3.7 GFlop/s!







• For variant 2 of the MVM: Performance in MFlop/s

Comments:

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- "no OpenMP" → variant 2 compiled without OpenMP
- Conclusion: compiler stops making certain serial optimizations if OpenMP switch is toggled





Outer loop unrolling

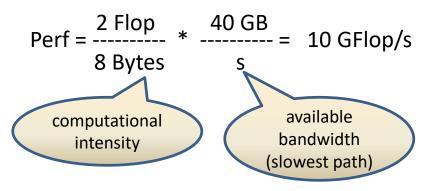
<pre>!\$omp parallel do reduction(+:r) DO k = 1, n-3, 4</pre>					
DO $j = 1$, n					
r(j) = r(j) + M(j, k) * x(k)					
+ M(j, k+1) * x(k+1) &					
+ M(j, k+2) * x(k+2) &					
+ M(j, k+3) * x(k+3)					
END DO					
END DO					
!\$omp end parallel do					

- conditioning omitted
- asymptotically increases intensity to 2 Flops per word (1 load on matrix per original loop iteration)

Unrolling is **limited** by number of available registers and prefetch streams (architecture-dependent!)

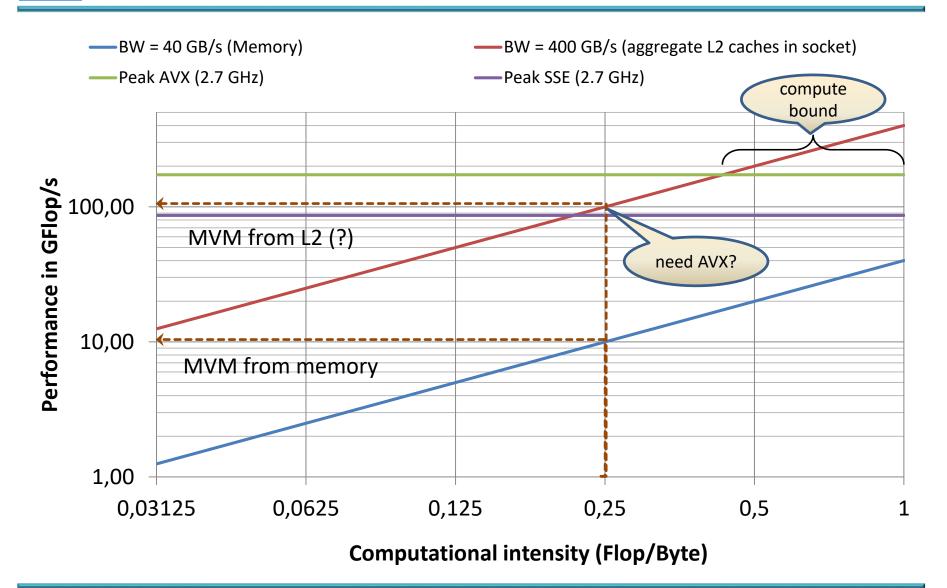
Expected performance

- for M from memory (i.e. outside any cache)
- contiguous streaming of data
- assuming 40 GB/s bandwidth for a socket



 estimation method is known as "Roofline Model"



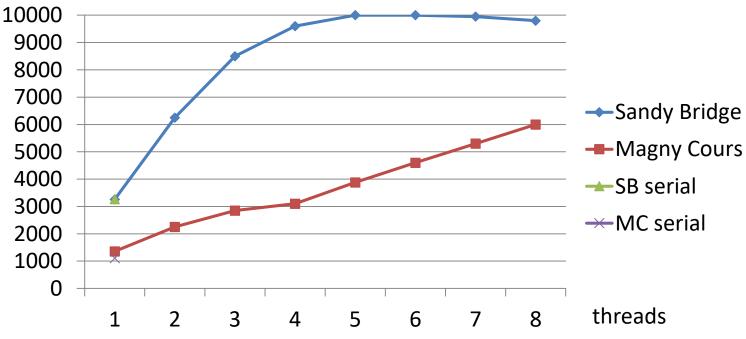


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In MFlop/s. Unroll factors: Sandy Bridge 4, Magny Cours 8



Comment:

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- roofline model only predicts "saturated" performance
- single-thread performance is limited by non-overlapping memory/core operations (see ref. (2))





- ... if variant 2 gives us the full performance anyway?
 - even if this only is attained with 8 threads

Possible reasons:

- "switch off" cores 6-8 to save energy (relevant for you if this is budgeted – may happen not too far in the future!)
- use cores 6-8 for other tasks that are cache bound
- use cores 6-8 for MPI communication (I/O via PCI) if you do hybrid programming (i.e., combine MPI with OpenMP)





References





- (1) OpenMP 4.5 standard and examples (currently 4.0.2) at http://openmp.org/wp/openmp-specifications/
- (2) Parallel programming in OpenMP

Rohit Chandra et al; Morgan Kaufmann 2000

- (3) Using OpenMP portable shared memory parallel programming
 - B. Chapman, G. Jost, R. van der Pas; MIT Press 2008
- (4) J. Treibig, G. Hager, G. Wellein: LIKWID

A lightweight performance-oriented tool suite for x86 multicore environments. PSTI2010, Sep 13-16, 2010, San Diego, CA DOI: 0.1109/ICPPW.2010.38; Preprint: <u>http://arxiv.org/abs/1004.4431</u>

- (5) G. Hager, J. Treibig, J. Habich, and G. Wellein: Exploring performance and power properties of modern multicore chips via simple machine models. Preprint: arXiv:1208.2908
- (6) G. Hager, G. Wellein: Introduction to High Performance Computing for Scientists and Engineers. Chapman & Hall / CRC (2011)





Appendix: Setting up Vtune Amplifier



Tuning of serial and threaded programs

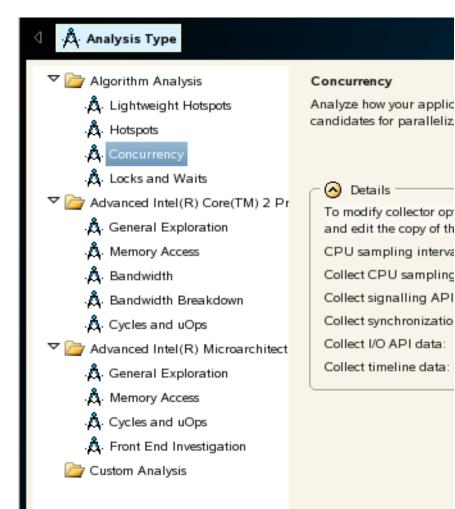
- performance counter access requires group rights
- Start up GUI
 - prerequisites: set up environment and possibly stack limit
 - then, invoke the GUI with amp1xe-gui &
 - command line amplxe-cl is also available, but will not be discussed
- Project generation analogous to Intel Inspector





```
#pragma omp parallel private(seed,i,k,me)
  ł
    me = omp_get_thread_num();
    seed = 123 + 159*me;
    for (k=0; k<100000; ++k) {
#pragma omp for
      for (i=0; i<10000; ++i) {
        ir[i] = rand_r(\&seed) \& 0xf;
      }
#pragma omp master
      for (i=0;i<10000; ++i) {
        hist[ir[i]]++;
      }
#pragma omp barrier
// prevents ir from being modified
// before hist update is done
```





Various types are provided

- select "Concurrency"
- in the project properties, set OMP_NUM_THREADS to number of physical cores

Note:

performance quality evaluation assumes complete system is used

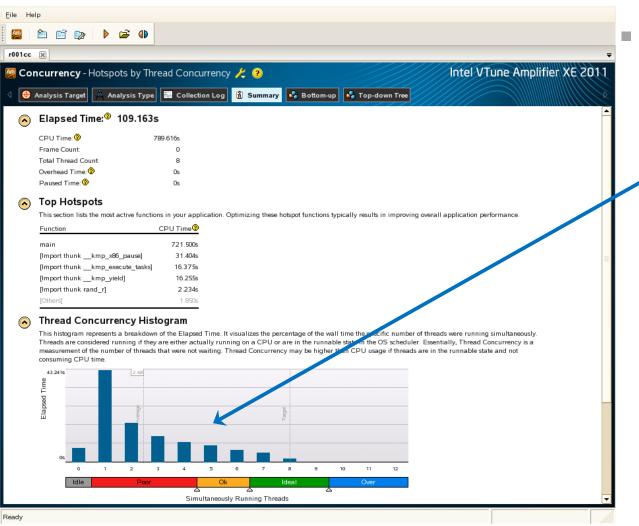
Note:

 analysis may take quite a long time to run, even for programs of small size



Result tabs: Summary



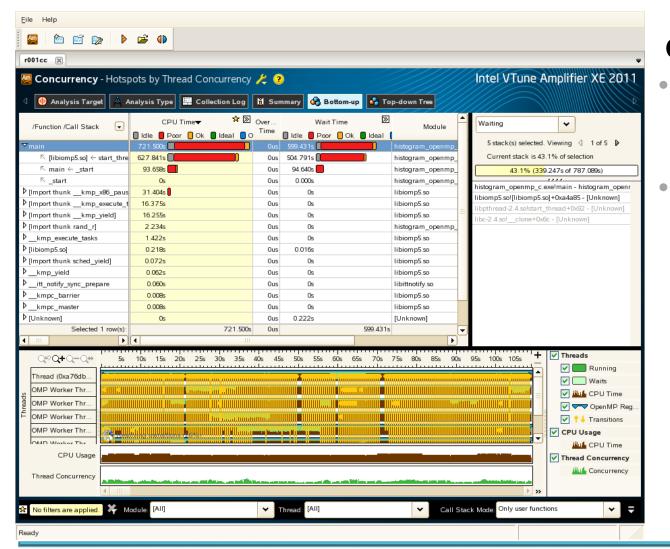


Result:

 thread concurrency very low although CPU usage is high







Observation:

- much time spent in OpenMP run time library
- lots of transitions
 indicated → have
 false sharing





Click on routine with significant resource usage

Sou	rce Assembly) 🤣 🛃 🗉			
Line	Source	CPU Time 🖈 🕅 🔲 Idle 📕 Poor 📙 Ok 🛢 Ideal 🛑 C	Over Time		
19	// cannot exactly reproduce serial res				
20	// but with fixed thread number result				_
21	// between runs			many updates to	
22	for (k=0; k<100000; ++k) {	0.024s		small shared variable	
23	#pragma omp for	0.048s			
24	for (i=0; i<10000; ++i) {	0.909s			
25	<pre>ir[i] = rand_r(&seed) & Oxf;</pre>	20.648s			
26	}	343 8166		295.518s	
27	#pragma omp master	0.054s			
28	for (i=0;i<10000; ++i) {	0.558s			=
29	hist[ir[i]]++;	0.570s			
30	}				
31	#pragma omp barrier	354.878s		303.912s	
32	<pre>// barrier prevents ir from being modi</pre>				
33	}				
	Selected 1 row(s):				•
	< III >				